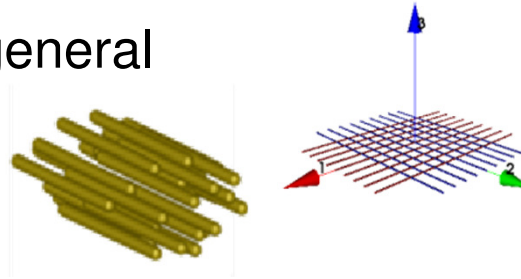


About the Coupling of DIGIMAT to LS-DYNA – a Micro- / Macro Interface for Composite Materials

Christian Liebold
DYNAmore GmbH

Dr. Jan Seyfarth
e-Xstream

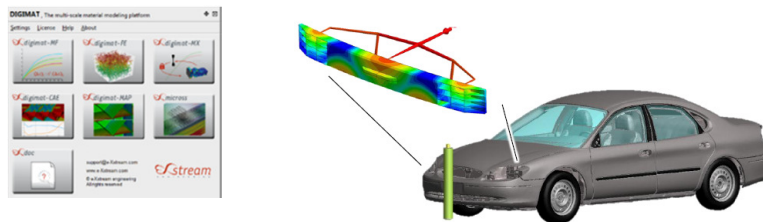
- Composites in general



- The DIGIMAT approach – Micro-/Macro Coupling



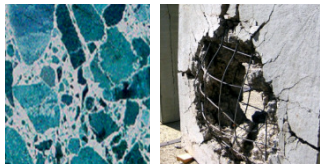
- DIGIMAT – Tools and Applications



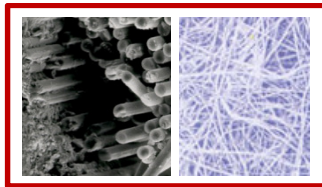
- Conclusion

Composites

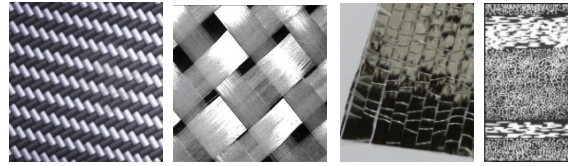
Definition: **Composite materials**, often shortened to composites or called composition materials, are **engineered** or **naturally** occurring materials made from **two or more constituent materials with significantly different physical or chemical properties** which remain separate and distinct within the finished structure.



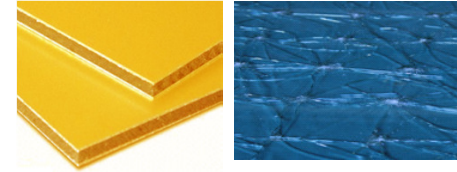
Concrete
(cement/stone/steel)



Short fiber
reinforced polymers
(glass/PP)



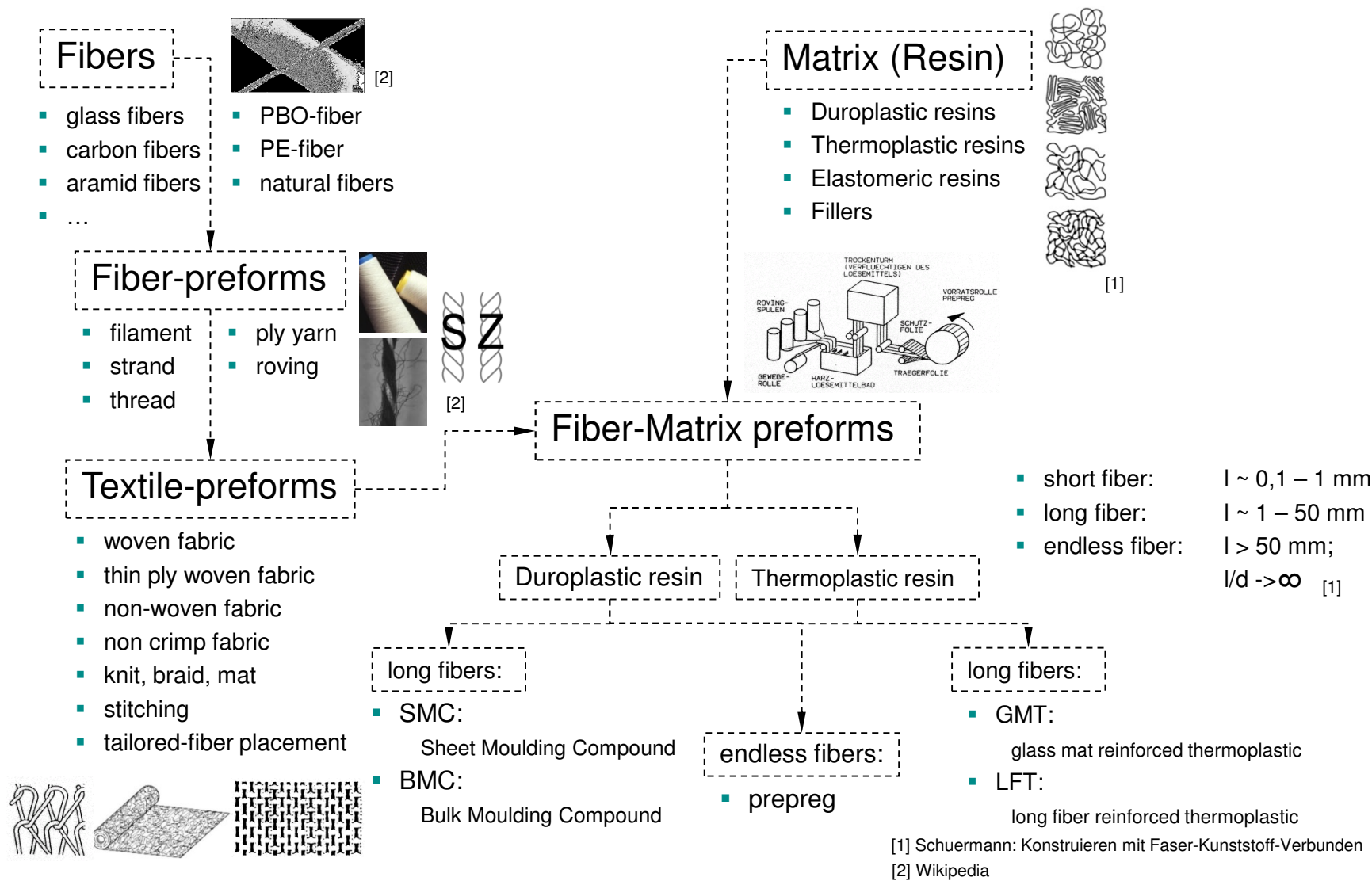
Long fiber
reinforced polymers
(glass/carbon/PA/PP/EP)




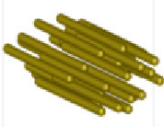
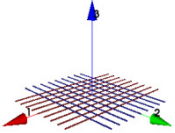
Sandwich/Laminates
(alloy/polymer/..glass/PVB/...)

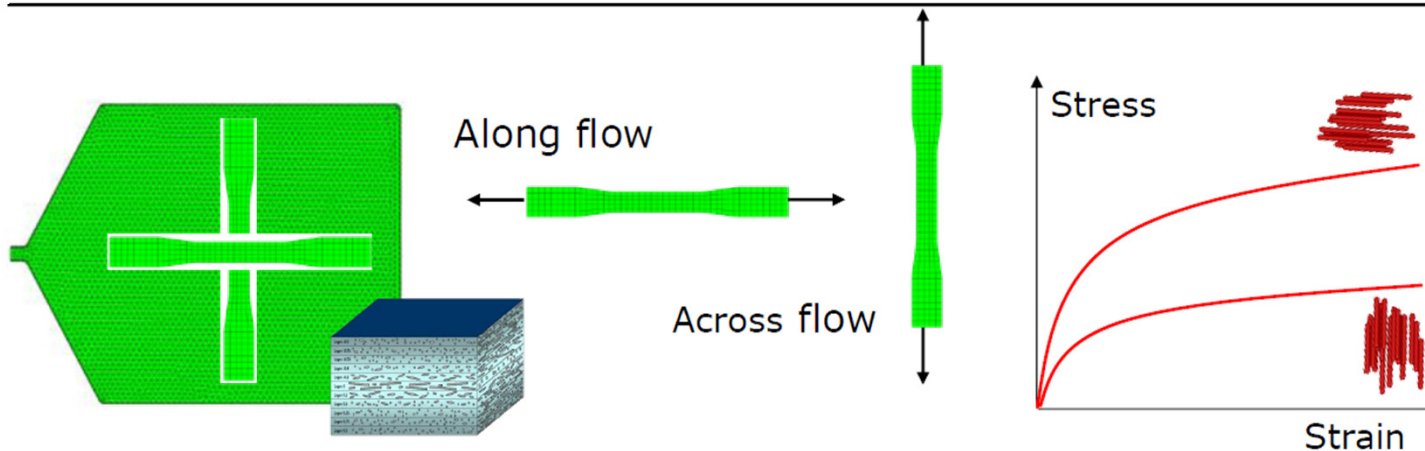


Composites



Composites

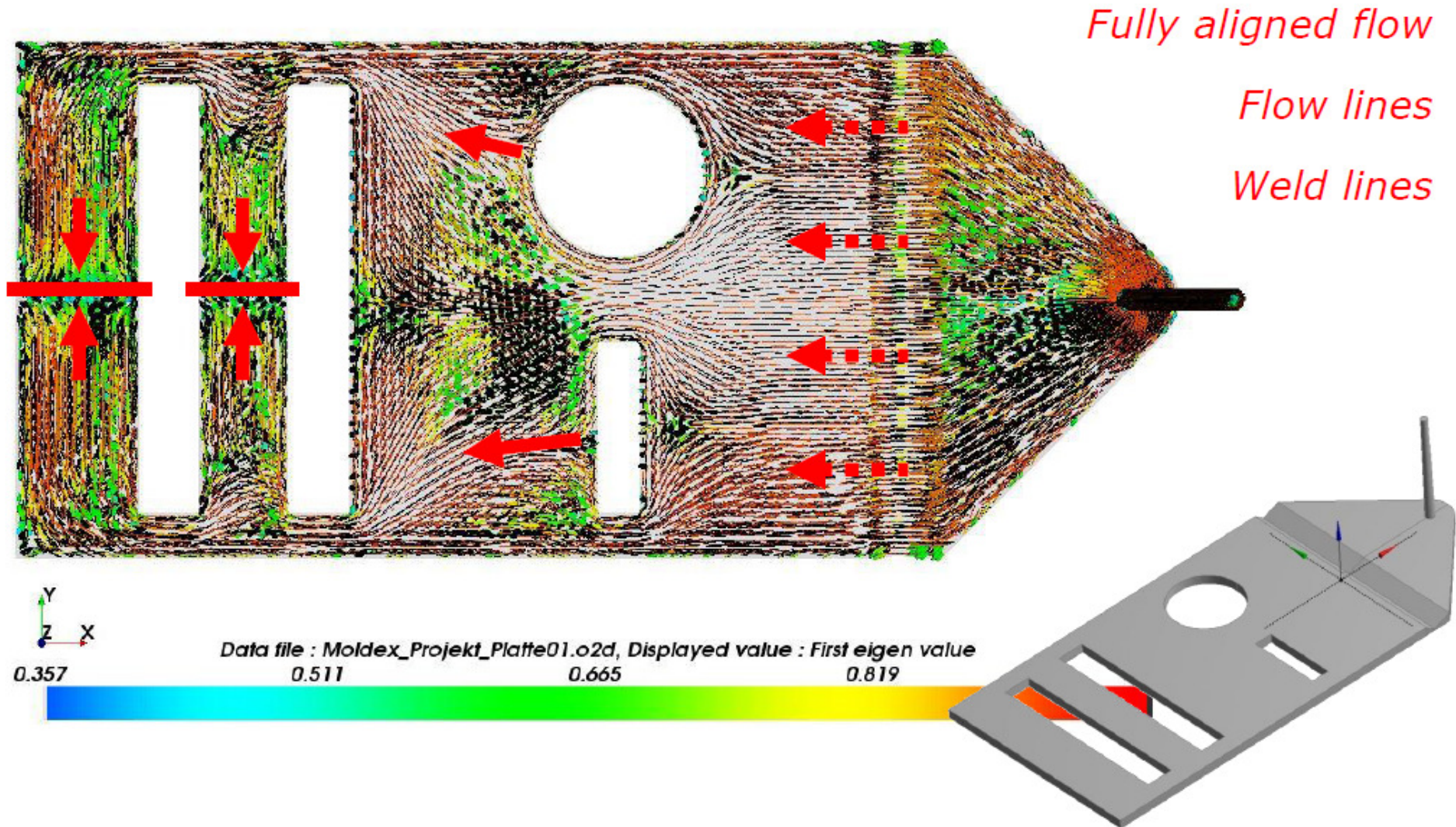
	MATERIALS		MICROSTRUCTURE			PROCESSING
	Matrix	Fibers	Inclusion	Orientation	Setup	Technology
Short fibers 	Thermoplast	Glass (Carbon)	Straight	Random	Skin/core	Injection molding
Long Fibers 	Thermoplast Thermoset	Glass Natural	Straight Wavy	Random Bundling	Complex Layers	Injection molding Compression molding
Continuous Fibers 	Thermoset (Thermoplast)	Glass Carbon	Straight	Fixed	Stacked	Draping



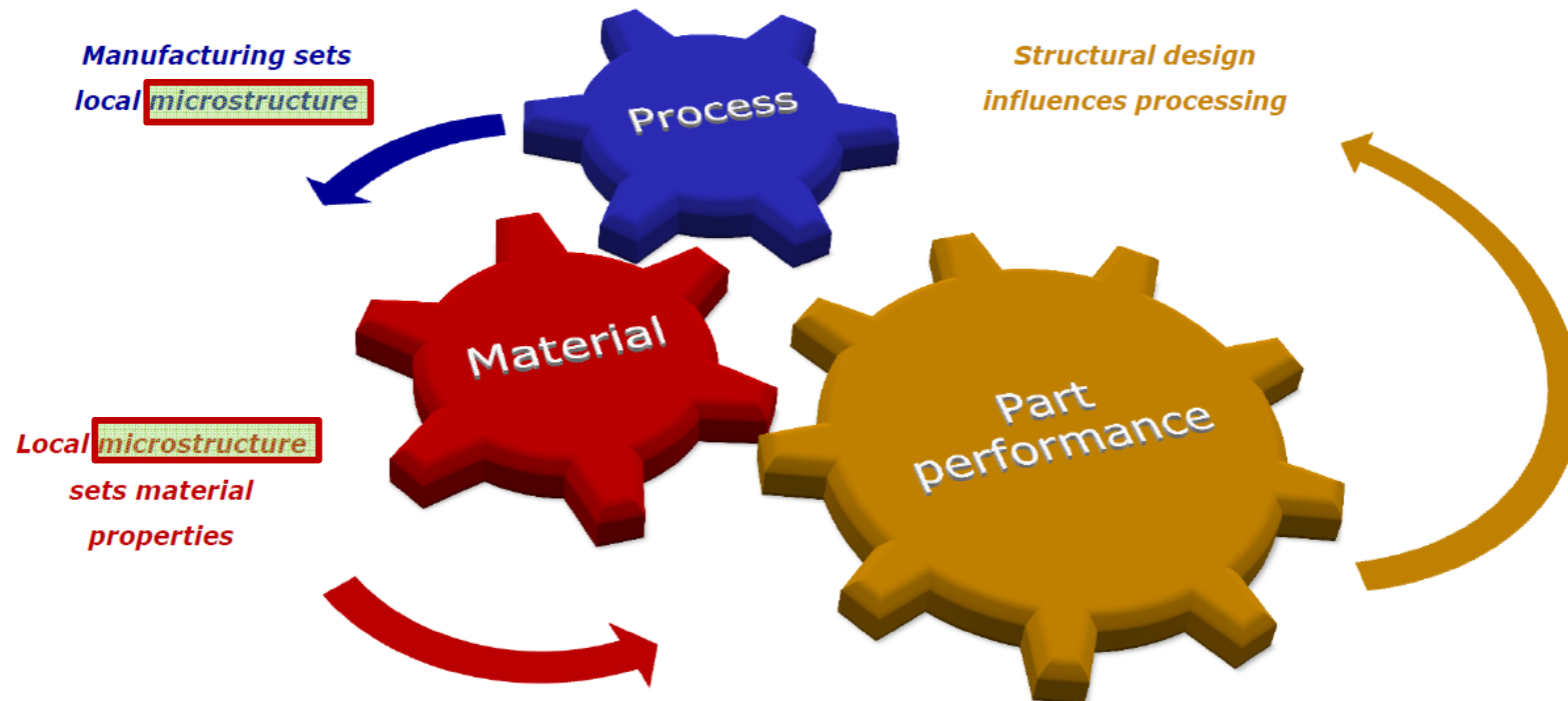
Composites



Capturing complex material properties

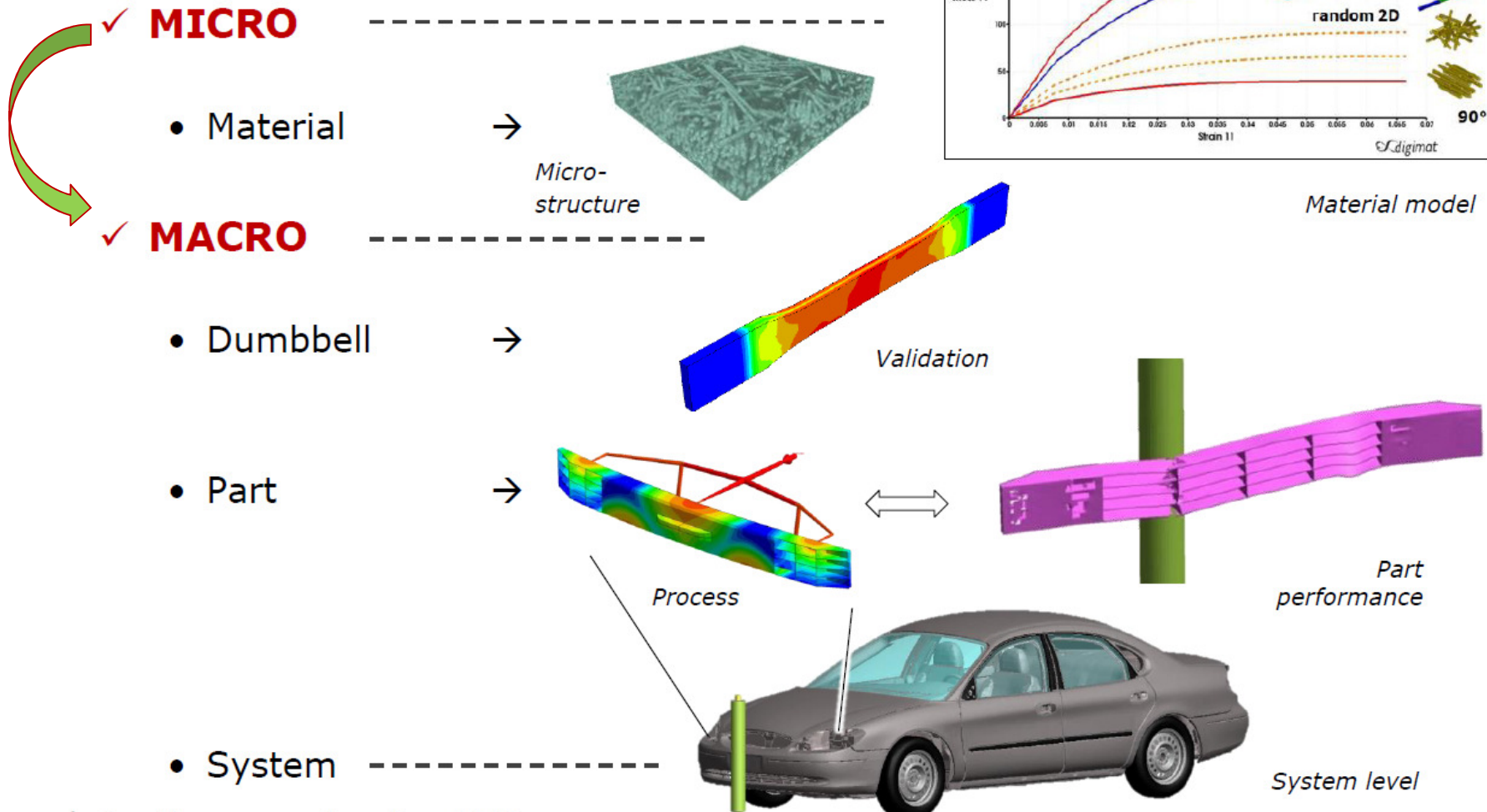


✓ Inter-dependencies in the Design of a Composite Part



DIGIMAT calculates the material behavior and performance on a **microstructural** basis.

Short Fiber Reinforced Plastics

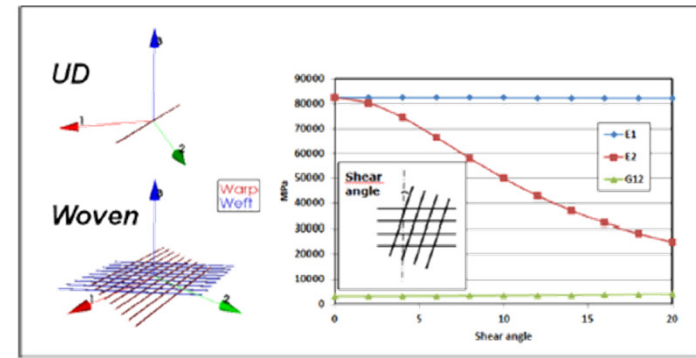
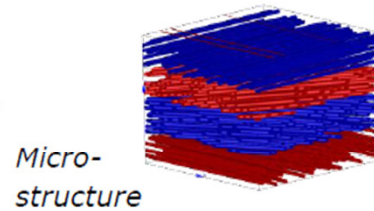




UD Composites

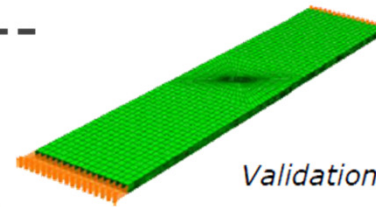
✓ MICRO

- Material

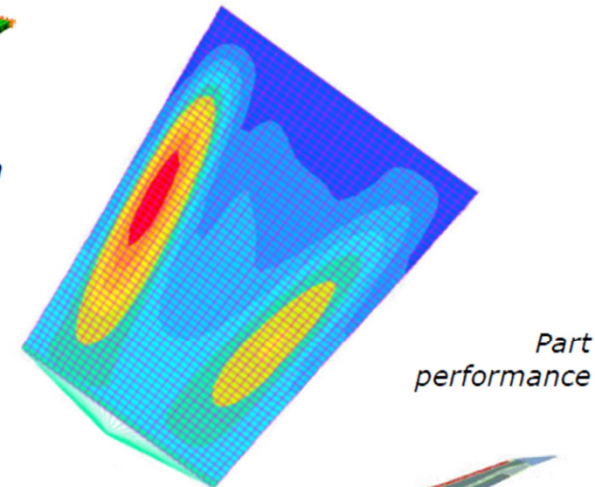
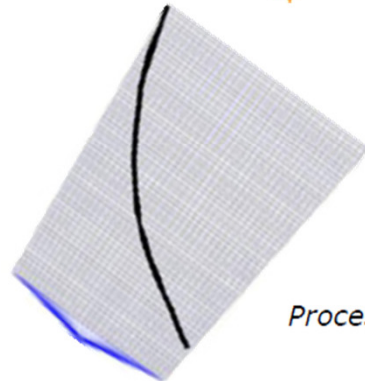


✓ MACRO

- Dumbbell



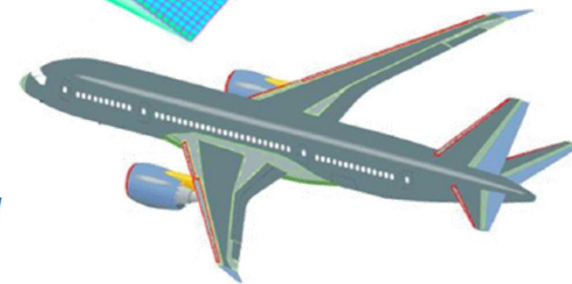
- Part



- System



System level





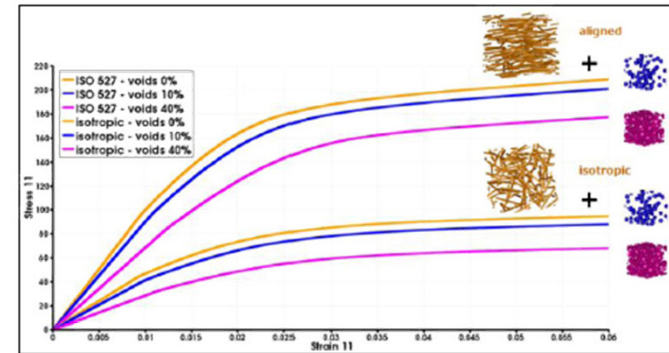
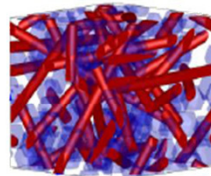
∞ Mucell

✓ MICRO

- Material



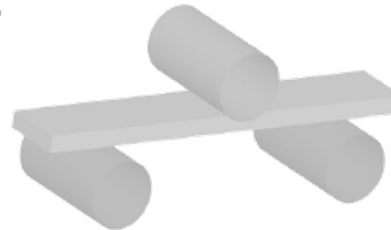
Micro-structure



Material model

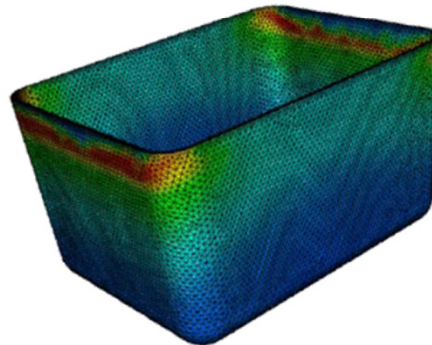
✓ MACRO

- Dumbbell

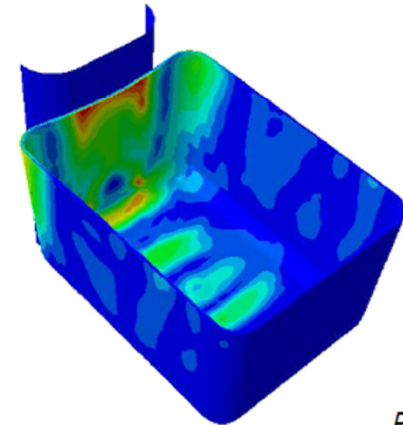


Validation

- Part



Process



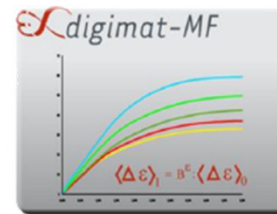
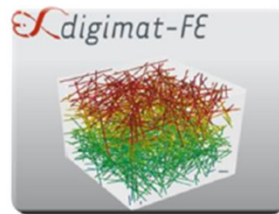
Part performance



∞ Nonlinear Multiscale Modeling Platform

✓ MICRO

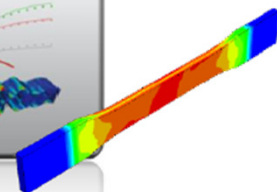
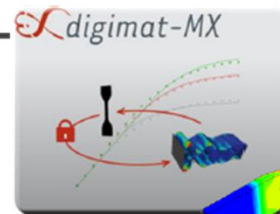
- Virtual Material



Material Engineering

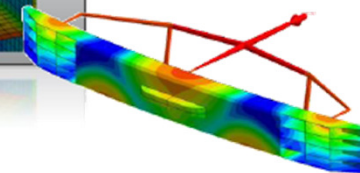
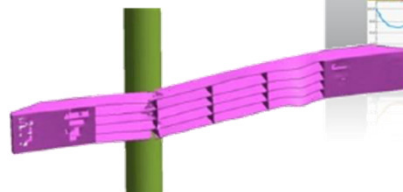
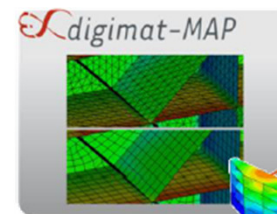
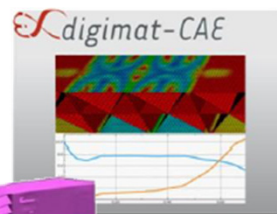
✓ MACRO

- Reverse Engineering

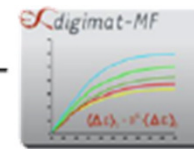
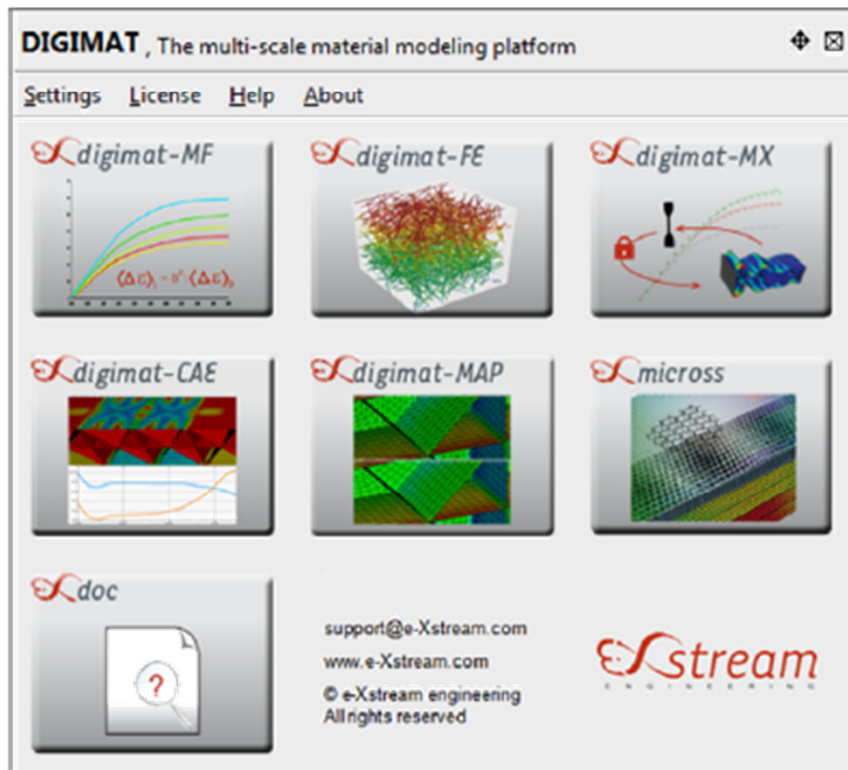


Structural Engineering

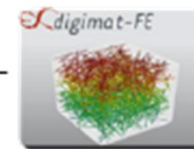
- Interfaces
- Mapping



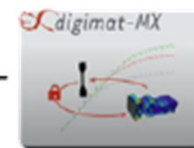
DIGIMAT-Tools & Applications



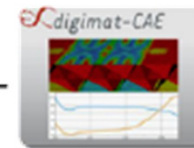
Digimat-MF
to predict the nonlinear constitutive behavior of multi-phase material.



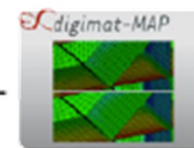
Digimat-FE
to perform Finite Element modeling of realistic Representative Volume Elements (RVE).



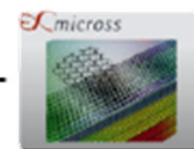
Digimat-MX
to reverse engineer, store, retrieve and securely exchange DIGIMAT material models.



Digimat-CAE
to interface to all major processing and structural FEA software codes.

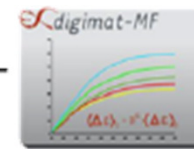
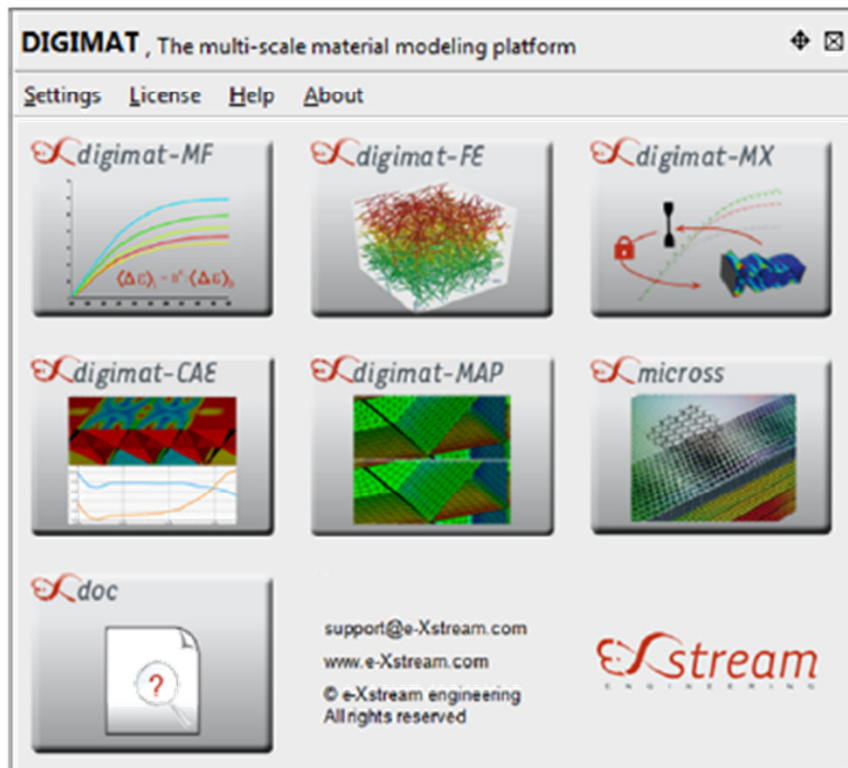


Digimat-MAP
to map data between dissimilar meshes.

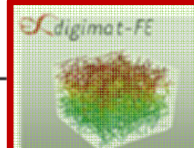


Micross
to design honeycomb core composite sandwich panels based on FE analyses.

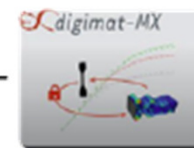
DIGIMAT-Tools & Applications



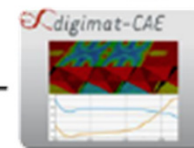
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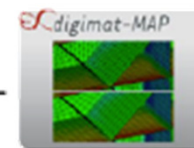
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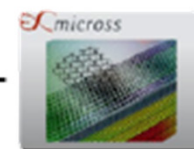
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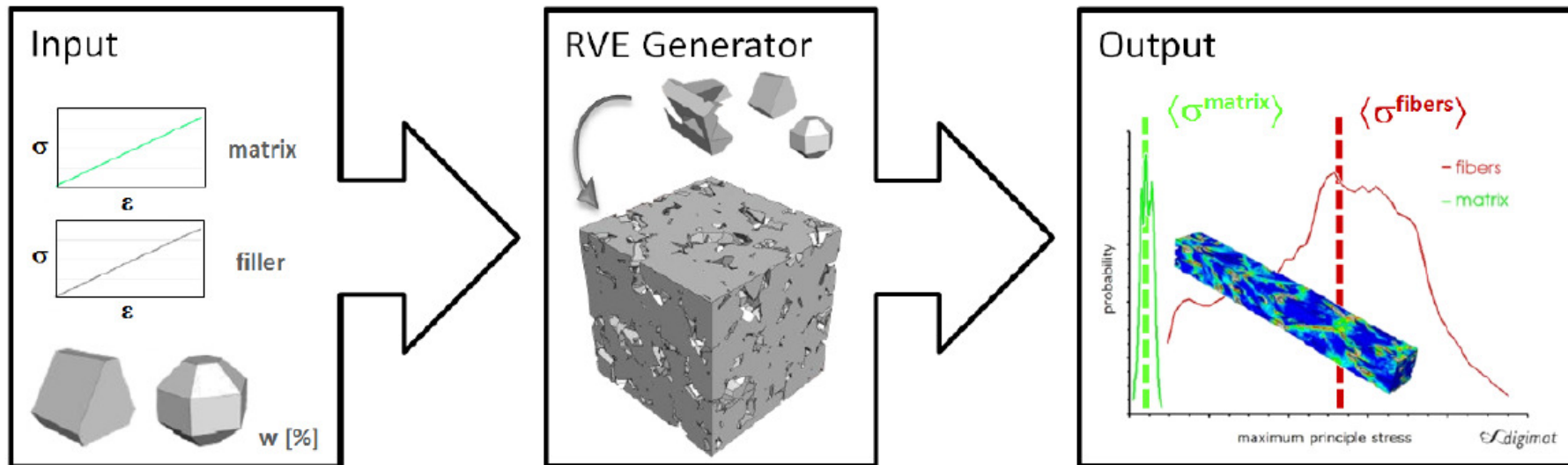
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RVE generation and in depth analysis



Per-phase material properties + microstructure information + RVE settings

Random creation of complex RVEs according to set of parameters

Pre: RVE with complex and realistic microstructure
 Post: analysis of result file from external FEA solver



RVE generation and in depth analysis

RVE Settings

RVE type

Single microstructure analysis: GFRP

Multilayer analysis

RVE size definition

Automatic

User defined

Size X1: 5

Size X2: 5

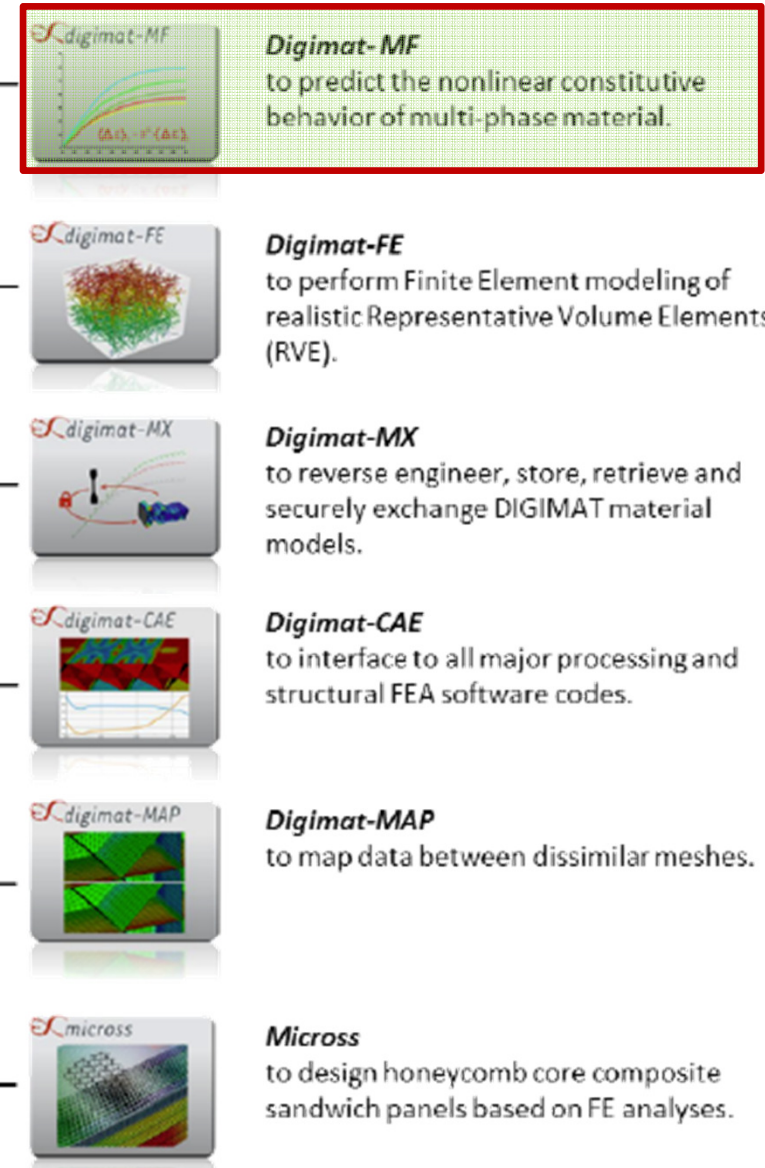
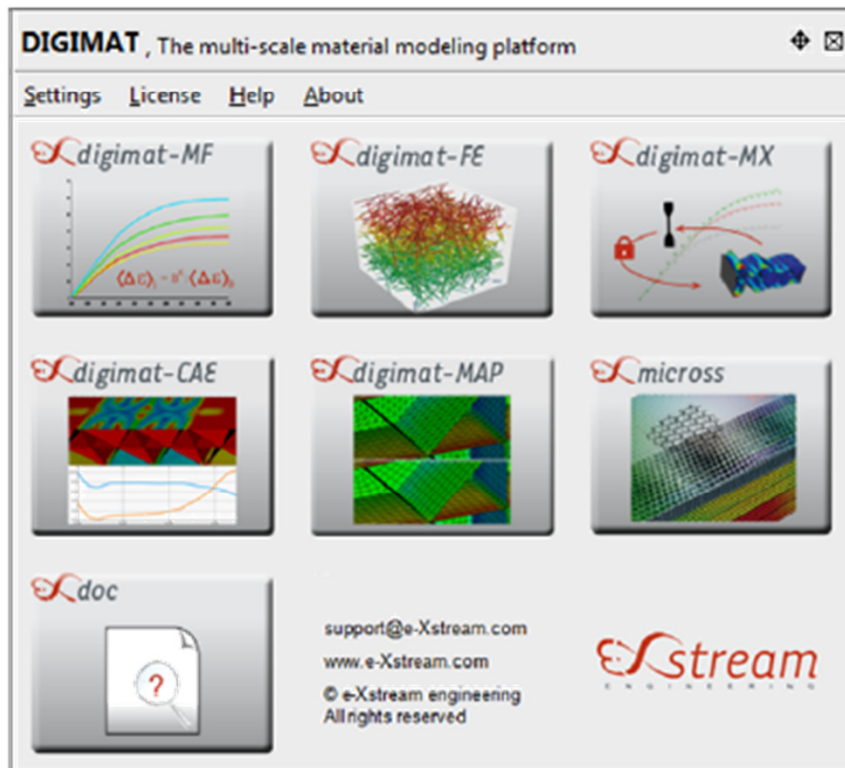
Size X3: 5

Get suggested RVE size

Multilayer definition

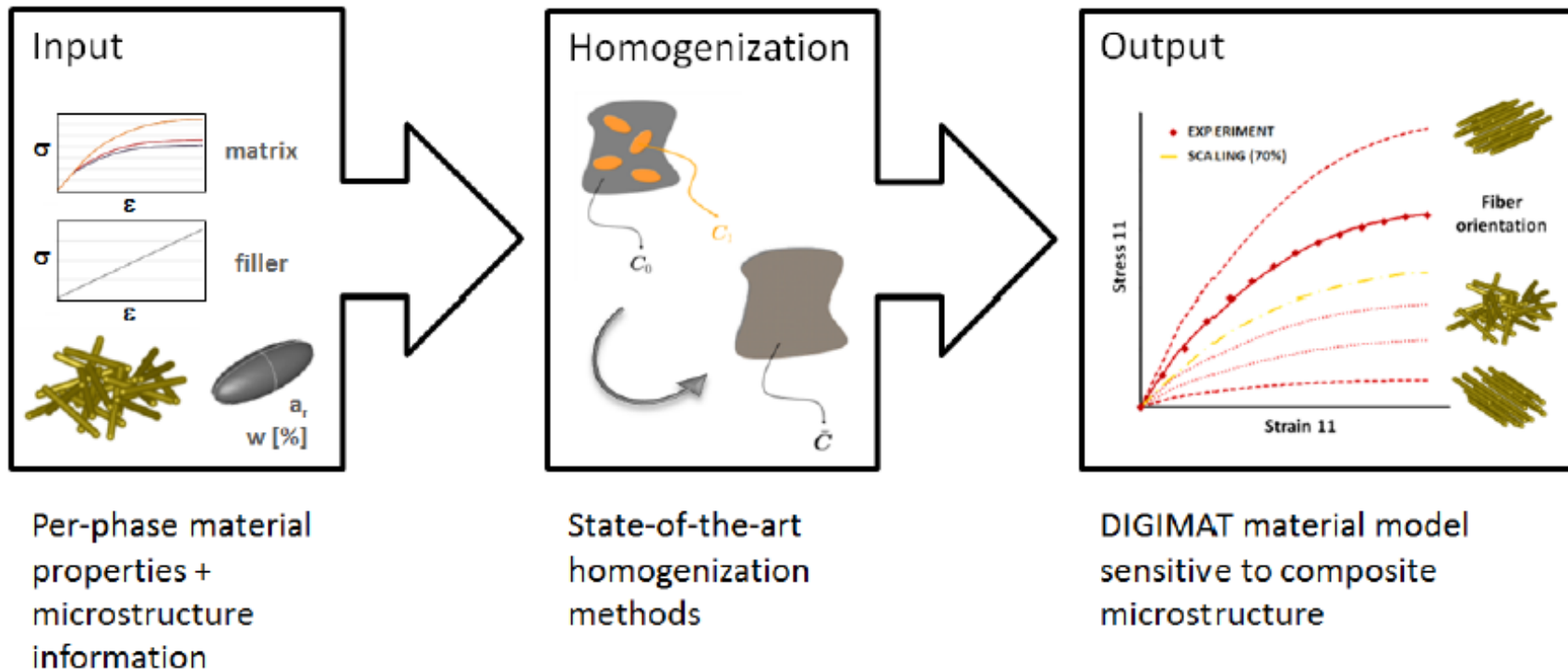
	Layer name	Microstructure	Thickness	Rotation	Orientation definition	Orientation
1	✓ Layer1	GFRP	1.25	0	From phase	
2	✓ Layer2	GFRP	1.25	90	From phase	
3	✓ Layer3	GFRP	1.25	45	From phase	
4	✓ Layer4	GFRP	1.25	-45	From phase	

- Output formats:
 - *.step
 - *.iges
 - *.breg
- Direkt link and meshing to:
 - ANSYS Workbench
 - Abaqus/CAE
- Different inclusion shapes & material models
- Different ways for microstructure definition (volume/mass content, multilayer, coating, orientation definition)
- Max. packing algorithm





- ✓ Material models dependent on the microstructure
 - Mori-Tanaka homogenization
 - Influence of fillers: amount, shape, orientation, ...

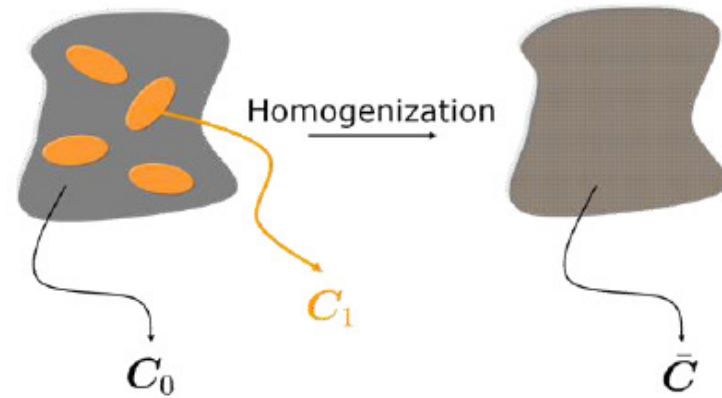




Multi-Phase Materials

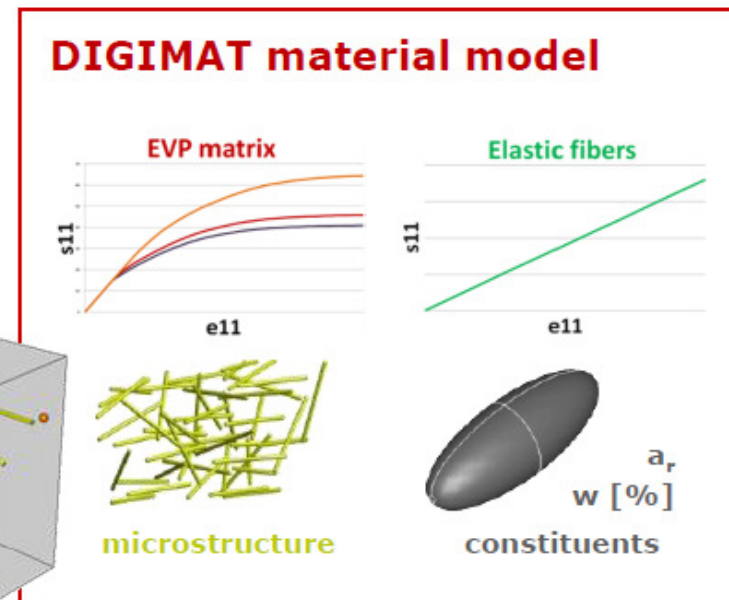
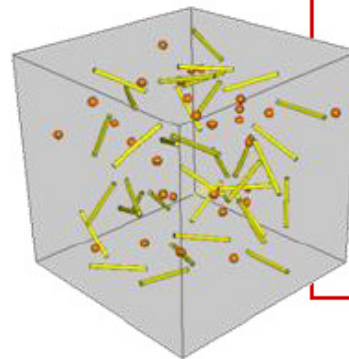
✓ Phases

- Material 1 [matrix]
- Material 2 [fibers]



✓ Microstructure

- Matrix
- Inclusions
 - Shape
 - Orientation





Material definition in MF

The screenshot shows the Digimat-MF software interface. On the left is a tree view of the project structure. The main window is titled 'Elastoplastic material' and contains several parameter input fields:

- General parameters:** Density: 1.31E-009
- Elastic parameters:** Young's modulus: 2430, Poisson's ratio: 0.4
- Plastic parameters:** Yield stress: 20
- Isotropic hardening parameters:** Hardening modulus: 25, Hardening exponent: 125, Linear hardening modulus: 100
- General options:** Isotropic extraction method: Spectral method, Plastic strain multiplier: 1, Plastic strain shift: 0, Global shear multiplier: 1, Plastic shear multiplier: 1

Below the parameters is a list of capabilities:

- Definition of the different materials
- strain-rate dependent
- temperature dependent

On the right, a graph titled 'Matrix' shows the material curve (S11 vs Strain 11). The curve starts at the origin, rises steeply to a yield point of approximately 20 at a strain of 0.01, then curves to a peak of about 48 at a strain of 0.05, and finally continues as a straight line up to a strain of 0.3 with a stress of approximately 72.

Below the graph are additional settings: Loading type: UNIAXIAL_1, Maximum strain: 0.3, and a 'Create' button.



Material definition in MF – matrix & inclusion definition

The screenshot shows the Digimat-MF software interface with the following parameters defined:

- Phase fraction:**
 - Volume fraction: 0.3 [0,1]
 - Mass fraction: 0.44991 [0,1]
- Shape parameter:**
 - Fixed aspect ratio: Value: 18
 - Aspect ratio distribution: Function: [dropdown]
 - Number of classes: 5
 - Inclusion radius: 1
- Orientation:**
 - Fixed: Theta: 90 ° Phi: 0 °
 - Random: Random 2D [dropdown]
 - Tensor:

a[1,1]	0.8	a[1,2]	0	a[1,3]	0
a[2,2]	0.15	a[2,3]	0	a[3,3]	0.05

Visualizations include a 3D red ellipsoid and a 3D coordinate system with axes 1, 2, and 3, showing the orientation tensor display type set to Ellipsoid.

- Definition of the inclusion's shape
- multiple reinforced faces
- ellipsoidal reinforcements
- aspect ratio distribution

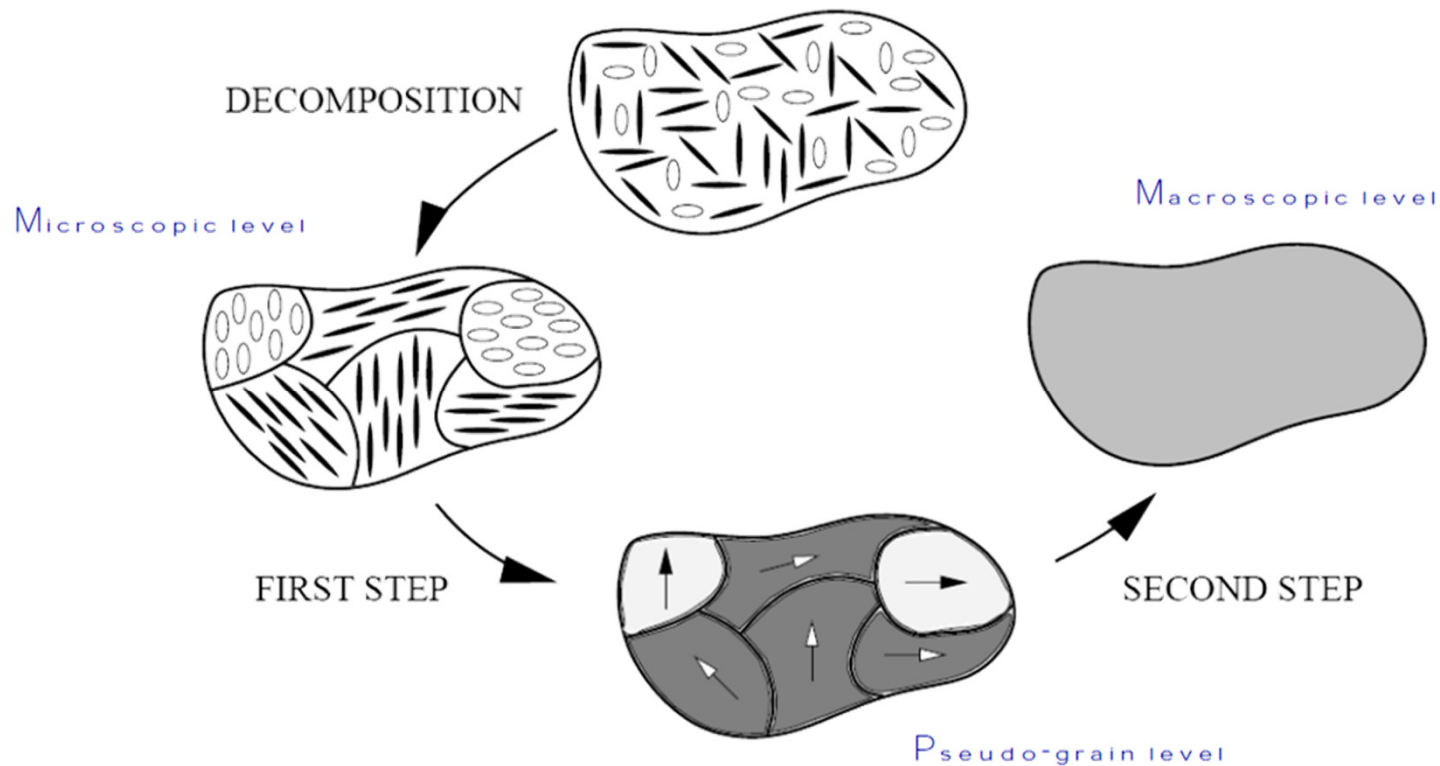
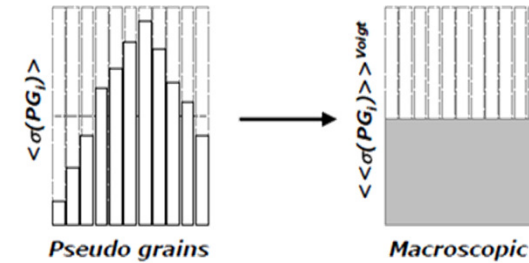
- Definition of orientation tensor
- multi-layer microstructures
- void inclusions
- coated inclusions
- deformable, quasi-rigid & rigid inclusions



Material definition in MF – homogenization

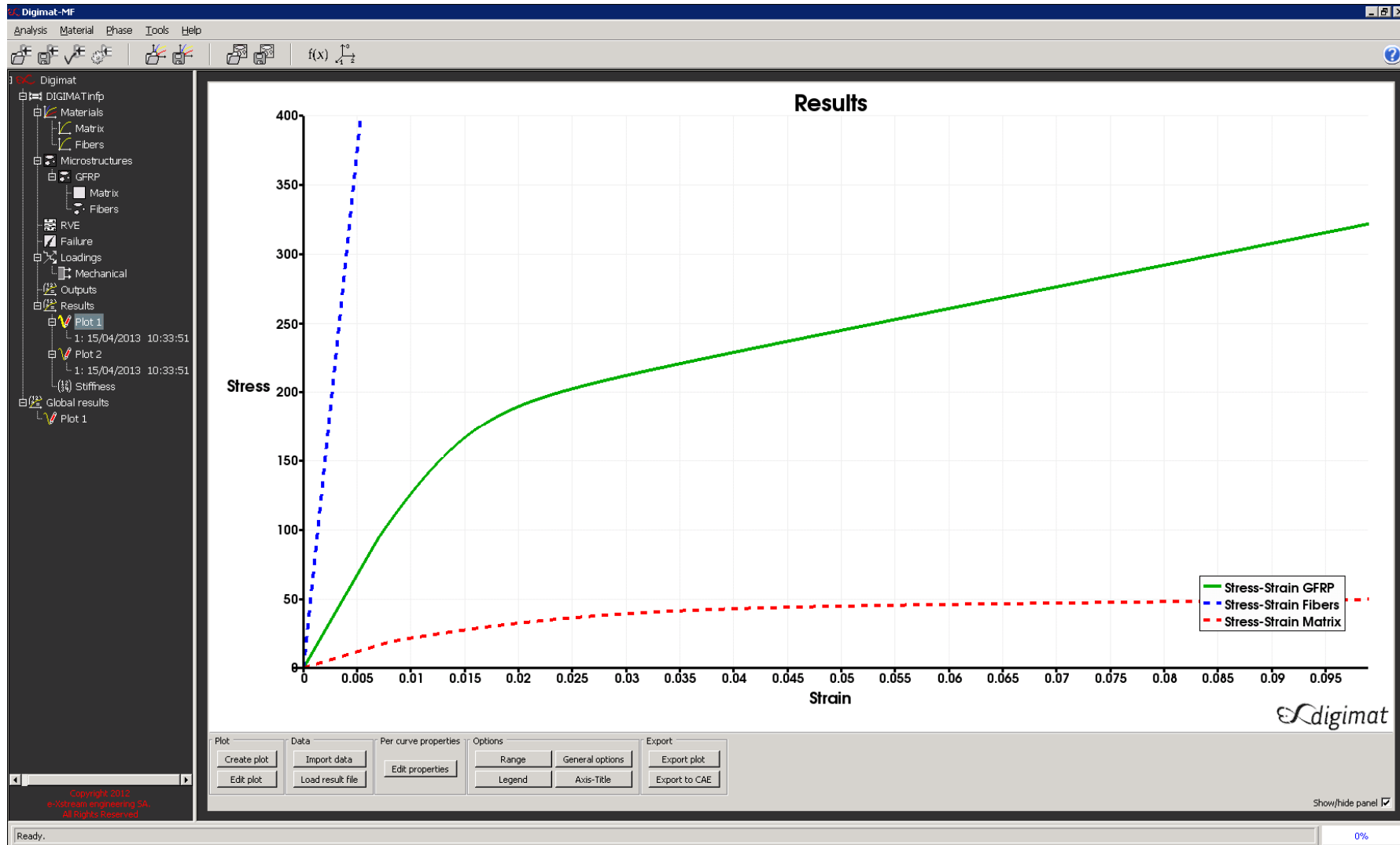
Multi-Phase Materials

✓ Stepwise homogenization





Material definition in MF – resulting parameter





Material definition in MF – resulting parameter

Global axes | **Local axes** | **Engineering constants**

DIGIMATinfp stiffness results

Compliance matrix

	11	22	33	12	23	13
11	7.4044E-005	-3.0412E-005	-2.616E-005	0	0	0
22	-3.0412E-005	0.00018602	-9.5979E-005	0	0	0
33	-2.616E-005	-9.5979E-005	0.00020037	0	0	0
12	0	0	0	0.00041701	0	0
23	0	0	0	0	0.00061065	0
13	0	0	0	0	0	0.00054151

Stiffness matrix

	11	22	33	12	23	13
11	17403	5336.3	4828.3	0	0	0
22	5336.3	8776.6	4900.7	0	0	0
33	4828.3	4900.7	7968.6	0	0	0
12	0	0	0	2398	0	0
23	0	0	0	0	1637.6	0
13	0	0	0	0	0	1846.7

Thermal expansion matrix

	1	2	3
1	Not available		
2			
3			

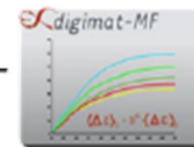
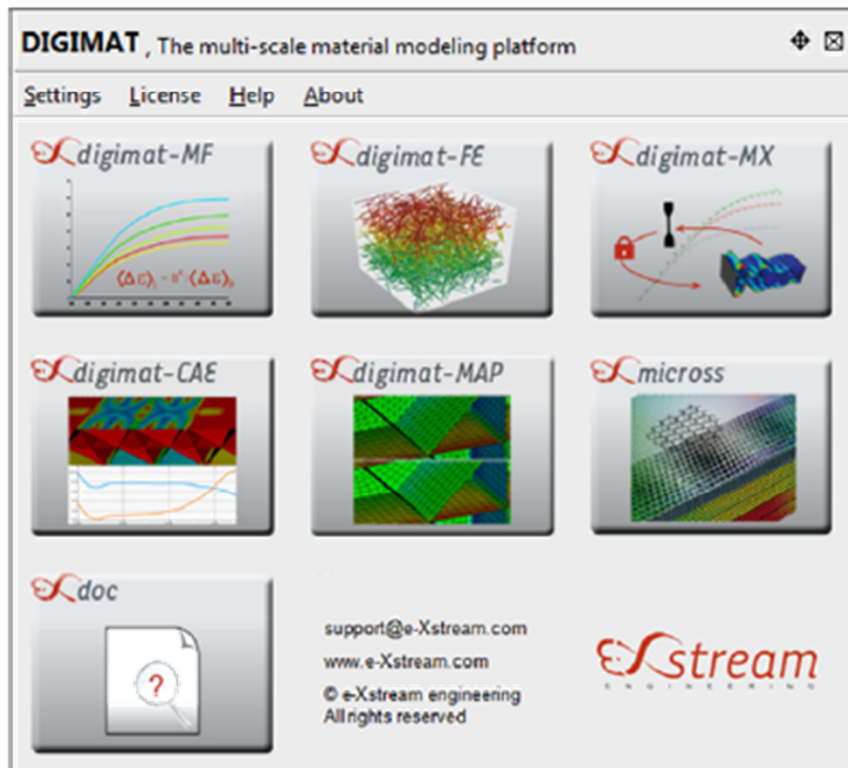
Engineering constants

	Value
Young's modulus E1	13506
Young's modulus E2	5375.6
Young's modulus E3	4990.7
Poisson's ratio 12	0.41074
Poisson's ratio 21	0.16349
Poisson's ratio 13	0.35331
Poisson's ratio 31	0.13056
Poisson's ratio 23	0.51595
Poisson's ratio 32	0.47901
Shear modulus 12	2398
Shear modulus 13	1846.7
Shear modulus 23	1637.6
Theta Angle 1	90
Phi Angle 1	0
Theta Angle 2	90
Phi Angle 2	90
Theta Angle 3	0
Phi Angle 3	90
Global density	1.667E-009

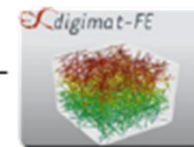
- Output of global & local axes
- Engineering constants
- Output can be user defined

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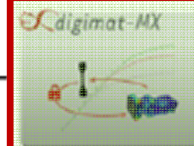
Ready. 0%



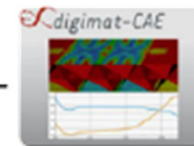
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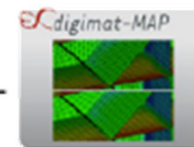
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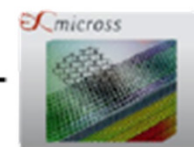
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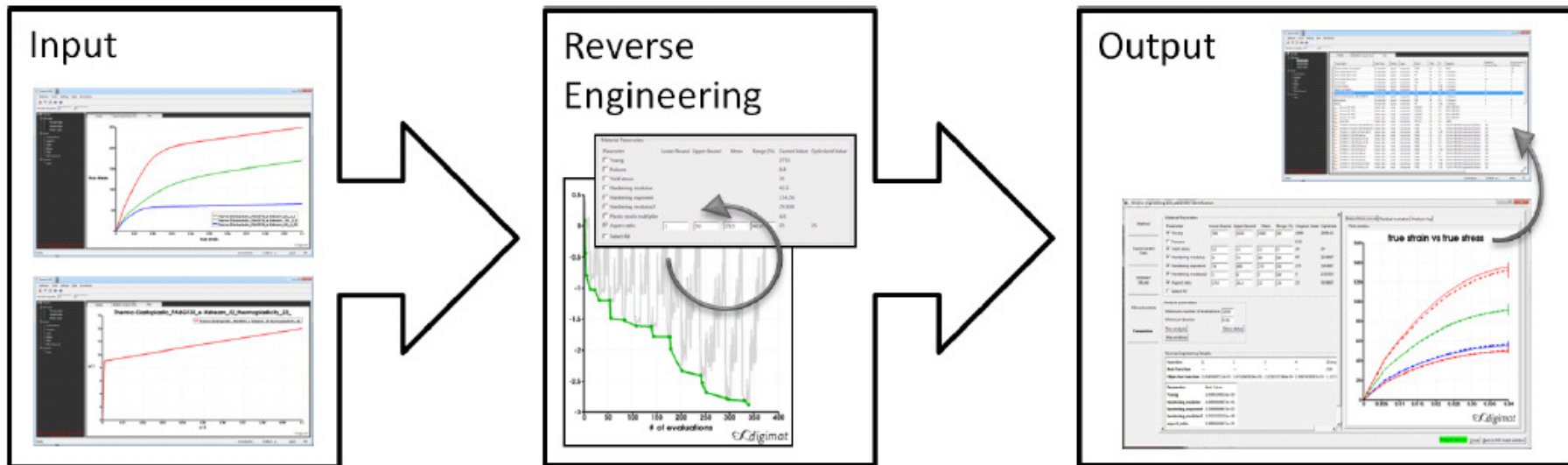
Digimat-MAP
to map data between dissimilar meshes.



Micross
to design honeycomb core composite sandwich panels based on FE analyses.



Parameter fitting in MX – overview



Experimental data, DIGIMAT material models stored in database

Calibration of DIGIMAT models based on experimental data

Calibrated DIGIMAT Material Model, stored in database and ready to be shared and used



Parameter fitting in MX – semi-quantitative approach

∞ „ISO 527“

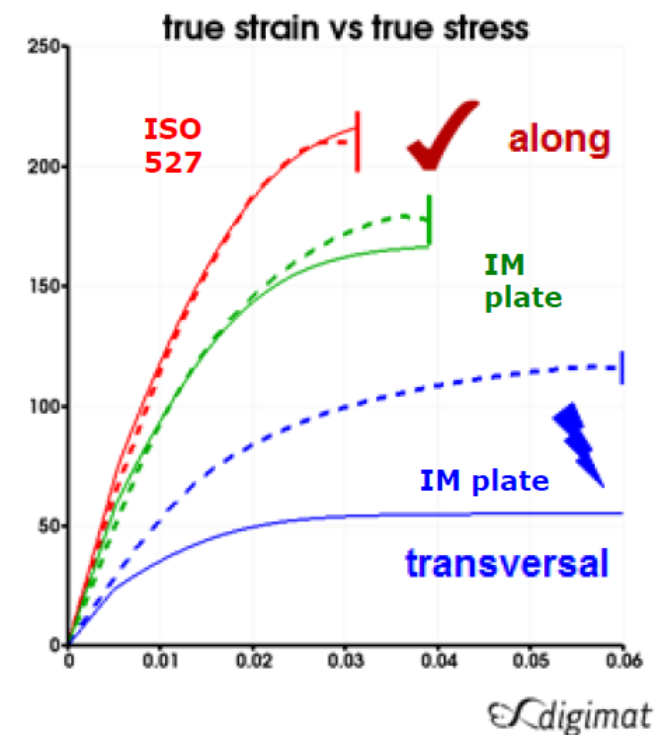


ISO527

✓ Short Fiber Reinforced Plastics

- **Semi-quantitative**

- Based on CAMPUS (or similar)
- **Non-expert**
- **Quick & easy**
- **Early design**
- Only stiffness
- Highly aligned states are better described than transversal





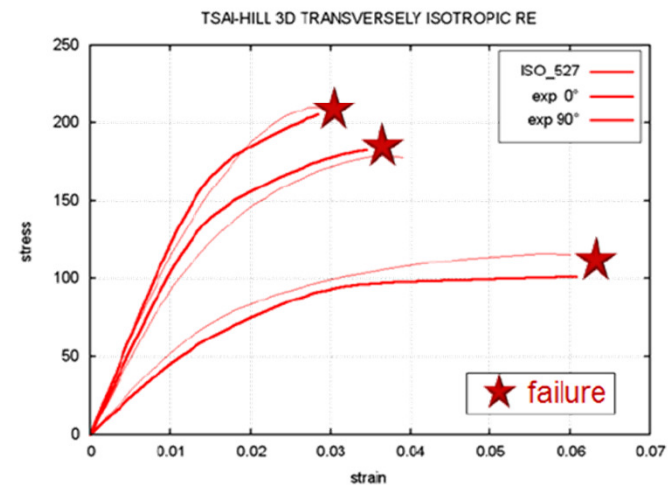
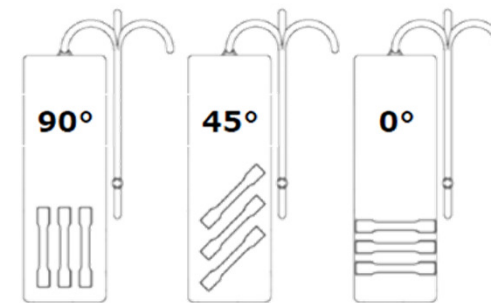
Parameter fitting in MX – qualitative approach

∞ „Injection Molded Plate“

✓ Short Fiber Reinforced Plastics

- Qualitative

- Based on anisotropic measurements
- **Expert**
- **Detailed**
- **Validation**
- Stiffness & failure
- Global fit of material behavior



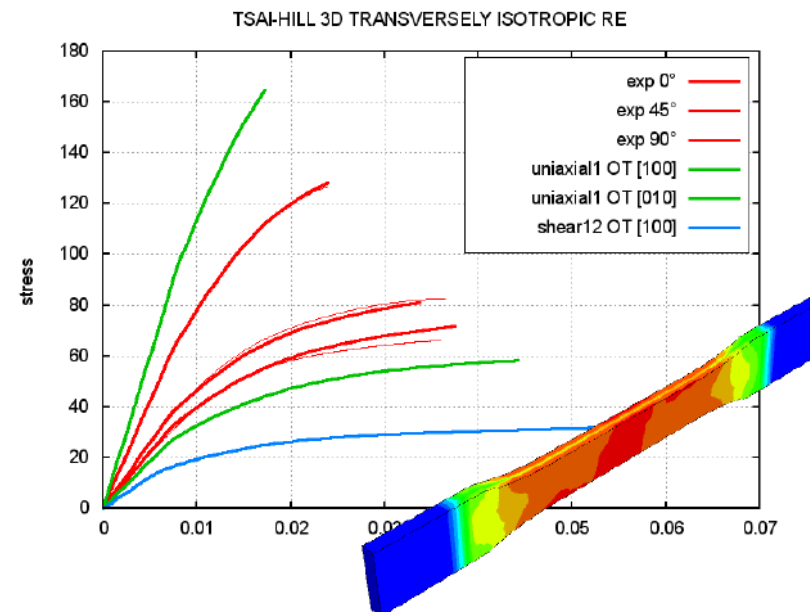
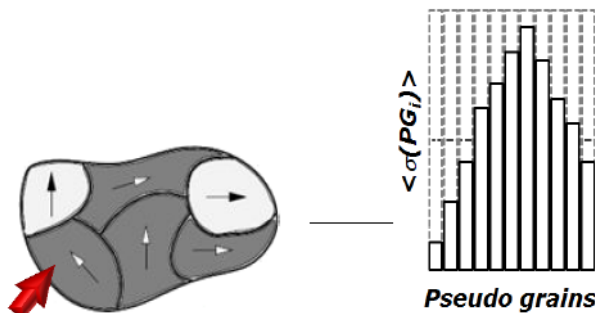


Parameter fitting in MX – qualitative approach

∞ „Injection Molded Plate“

✓ Short Fiber Reinforced Plastics

- Based on pseudo grains (FPGF)
- Described on composite level
 - Tsai-Hill 3D
 - Transversely isotropic
 - Strain based



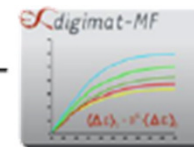
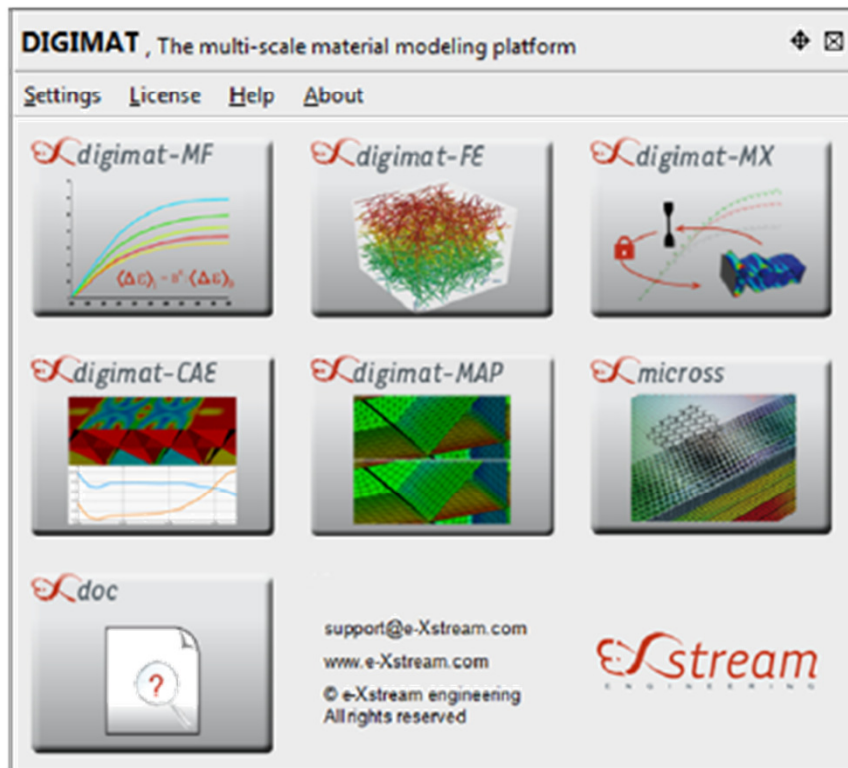


∞ Parametrize & eXchange DIGIMAT material models

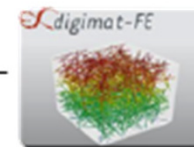
✓ Public data

- Ready-to-use DIGIMAT models
- Experimental data for parametrization of DIGIMAT models

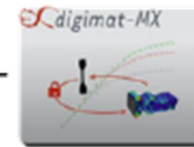




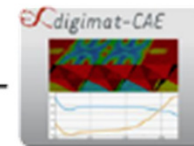
Digimat-MF
to predict the nonlinear constitutive behavior of multi-phase material.



Digimat-FE
to perform Finite Element modeling of realistic Representative Volume Elements (RVE).



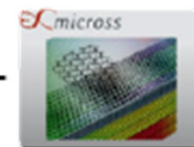
Digimat-MX
to reverse engineer, store, retrieve and securely exchange DIGIMAT material models.



Digimat-CAE
to interface to all major processing and structural FEA software codes.



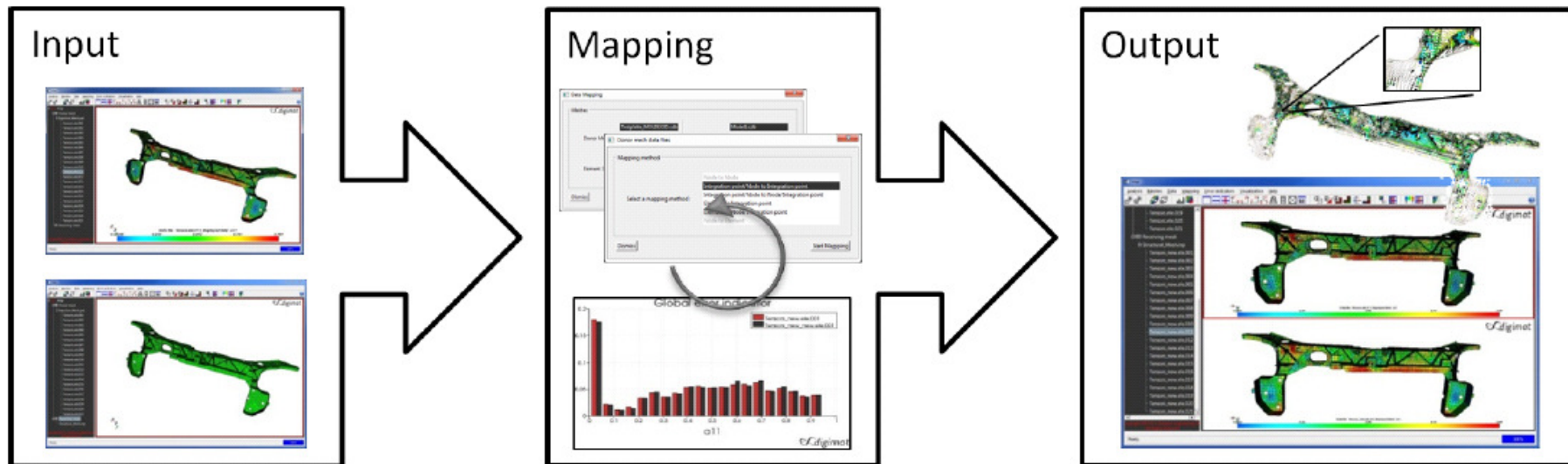
Digimat-MAP
to map data between dissimilar meshes.



Micross
to design honeycomb core composite sandwich panels based on FE analyses.



Mapping from process simulation onto crash mesh



Mesh & properties from processing simulation + Mesh for structural FEA

Robust mapping methods

Mapped properties on structural FEA mesh + strong visualization of results



Mapping from process simulation onto crash mesh

- From mid-plane to multi-layered shell
- Between continuum 3D elements
- Across the shell thickness

- Fiber orientation tensors
- Residual stresses
- Temperature fields
- Weld lines

- Donor:
 - Tetra or TRIA
 - Hexa & Wedge
- Receiver
 - Tetra or TRIA
 - Hexa or QUAD
 - Wedge

The screenshot displays the Digimat-MAP interface. The top window shows a process simulation mesh with a color scale ranging from 0.0192 to 0.954. The bottom window shows a crash mesh with a color scale ranging from 7 to 9. A green arrow indicates the mapping direction from the process simulation to the crash mesh. The software interface includes a menu bar (Analysis, Mesh, Data, Mapping, Error indicators, Visualization, Help) and a toolbar with various icons. The status bar at the bottom shows 'Ready.' and '100%'.



Mapping from process simulation onto crash mesh

Mesh: beam_study.pat , Data file: FullyFilled_ele , Current layer: 13

- DIGIMAT
- Moldex3D
- Moldflow Mid-Plane
- Moldflow 3D
- REM3D
- SigmaSoft
- 3D Timon
- SIMPOE

Displayed field : α_{33}

0.0192 0.253 0.487 0.721 0.954

Mesh: ImplicitModel.k , Data file: FullyFilled_new_ele , Current layer: 13

- Abaqus
- ANSYS
- Ideas
- **LS-DYNA**
- PAM-CRASH
- Patran
- Radioss
- REM3D
- SAMCEF
- 3D Timon
- Simulayt
- MSC.Marc
- Nastran Sol400

Ready. 100%

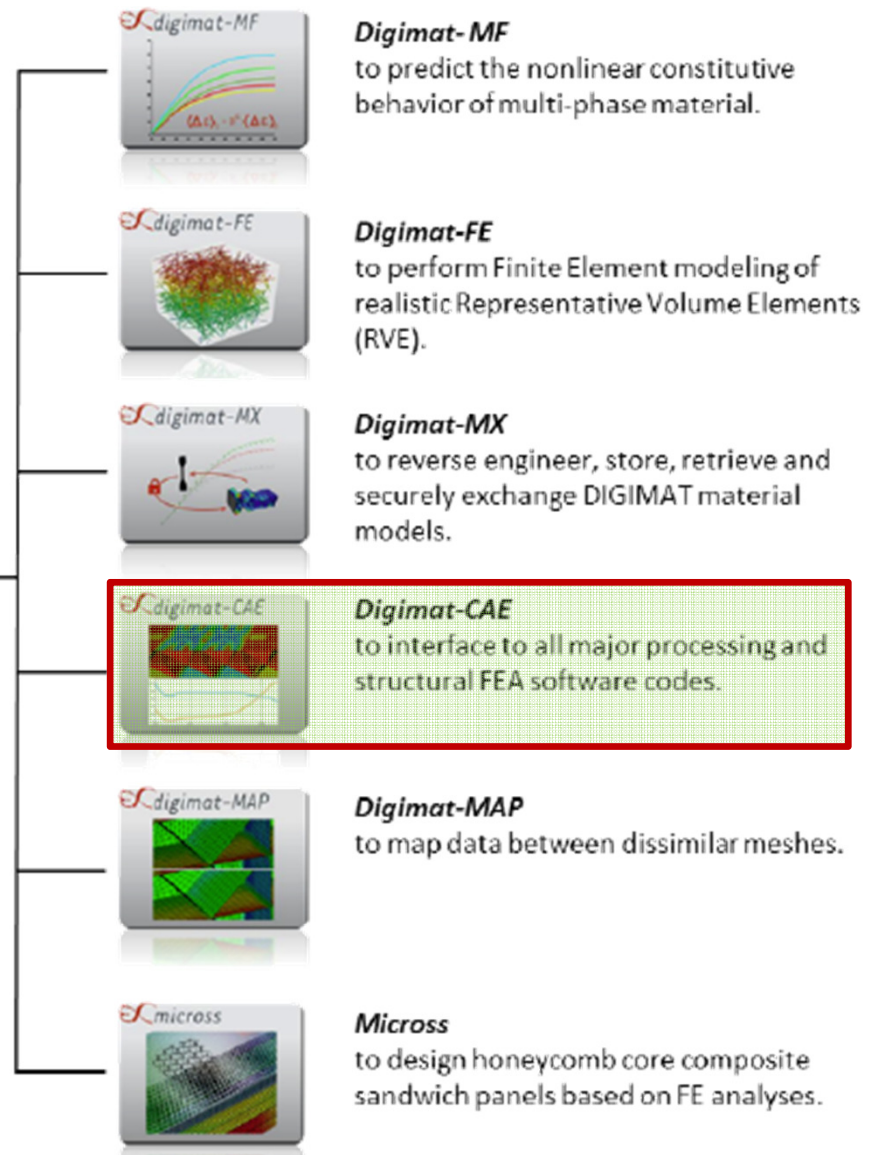
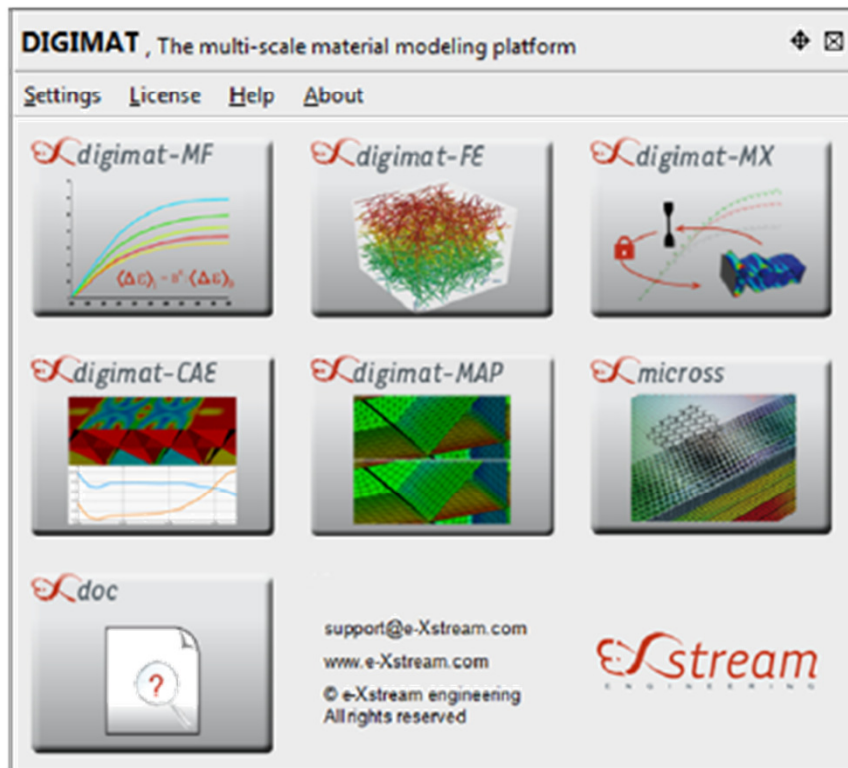


Mapping from process simulation onto crash mesh

The screenshot displays the Digimat-MAP software interface with two main panels. The top panel shows a 3D mesh of a beam structure with a color scale for 'Rel nb elem' ranging from 0.0192 to 0.954. To its right is a bar chart titled 'Global error indicator' comparing 'FullyFilled.ele (layer 13)' (red bars) and 'FullyFilled_new.ele (layer 13)' (black bars) across a range of α_{33} values from 0 to 1. The bottom panel shows a zoomed-in view of a mesh section with a color scale from 7 to 9, and a line graph titled 'FullyFilled_new_AbsError.err - Element 6791' plotting 'Thickness' against α_{11} .

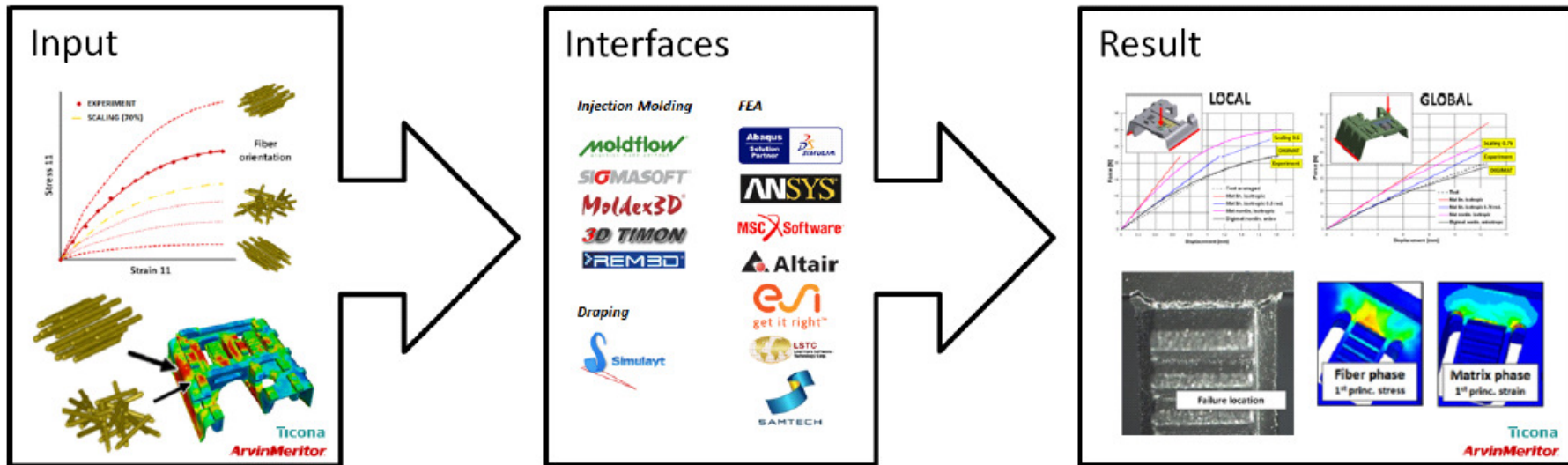
Global error indicator Data (Estimated):

α_{33}	FullyFilled.ele (layer 13)	FullyFilled_new.ele (layer 13)
0.0	0.00	0.00
0.1	0.00	0.00
0.2	0.00	0.00
0.3	0.00	0.00
0.4	0.01	0.01
0.5	0.05	0.05
0.6	0.06	0.06
0.7	0.23	0.23
0.8	0.40	0.40
0.9	0.19	0.17
1.0	0.00	0.00





Coupling Micro- & Macromechanics



DIGIMAT material model + local microstructure (from processing simulation)

Weakly or strongly coupled analyses with implicit or explicit FEA solvers

Predictive, high quality results for composite structures

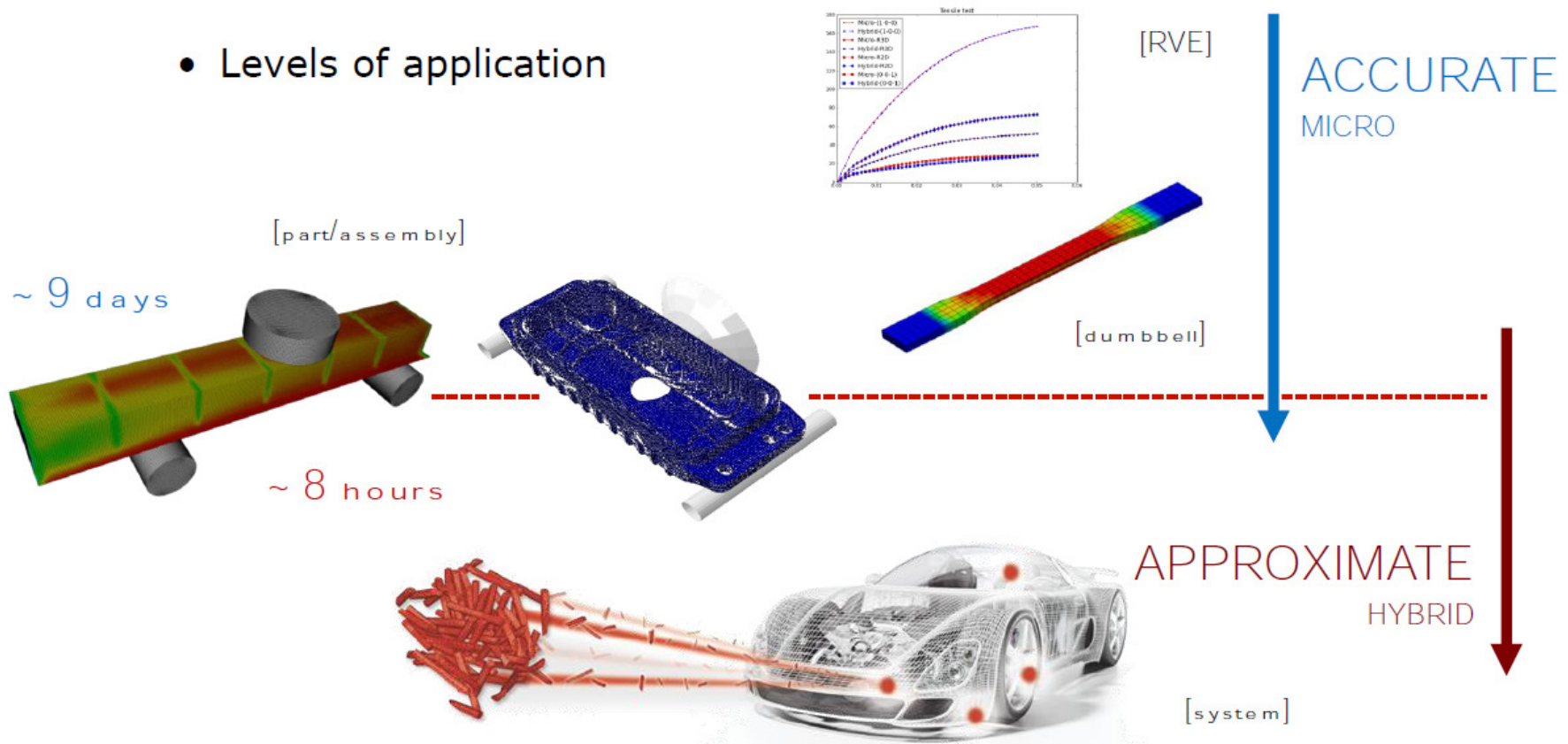


Micro - vs. Macro - Approach

✓ Hybrid approach: Trade-Off between accuracy and computation time

✓ CPU time can become critical

- Levels of application



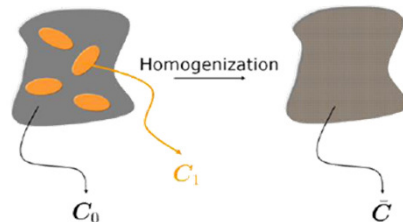


Micro - Approach

The full homogenization approach operates at each integration point & time of analysis

✓ Micro-/Macro Transition:

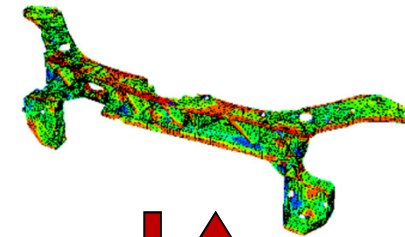
- Use of homogenization method to predict the macro constitutive behavior of the RVE.



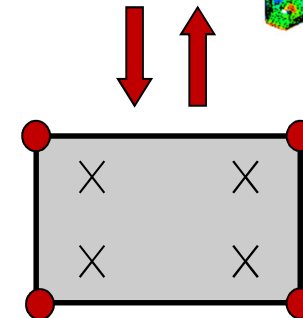
✓ Macro FEA:

- Perform classical continuum mechanics computations at macro scale with macro constitutive response.

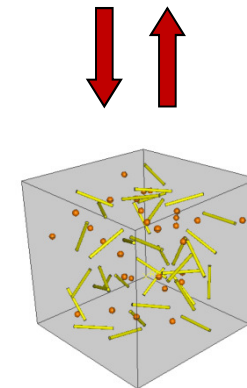
FE-model level:



Element level:



Material level:





Hybrid - Approach

Reduction of information exchange to the macroscopic level.

✓ Macroscopical properties are pre-computed

- DIGIMAT-CAE interface used to communicate with the structural code at each iteration of the overall computation
- Per-phase micro results are skipped
- Only available for two-phase composites so far
- Reverse engineering to deliver a good approximation to the exact micro solution

✓ Hybrid solution provides a great speed-up

- ~ 20 x for explicit analysis with elasto (visco-) plastic materials
- Further speed-up expected for release 4.4.1 (April 2013)
- No convergence trouble due to the skipped homogenization
- Failure is based on state-of-the-art **F**irst **P**seudo **G**rain **F**ailure (FPGF) model for randomly distributed short fibers



Including failure mechanisms

Failure indicator definition

Name: FailureIndicator1

Model: Tsai-Hill 3D Transversely Isotropic

Axes system: local axes

Failure indicator outputs

$$f_A = \frac{\sigma_{11}^2}{X^2} - \frac{\sigma_{11}(\sigma_{22} + \sigma_{33})}{X^2} + \frac{(\sigma_{22}^2 + \sigma_{33}^2)}{Y^2} + \left(\frac{1}{X^2} - \frac{2}{Y^2}\right)\sigma_{22}\sigma_{33} + \frac{(\sigma_{12}^2 + \sigma_{13}^2)}{S^2} + \left(\frac{4}{Y^2} - \frac{1}{X^2}\right)\sigma_{23}^2$$

Parameters

Axial tensile strength (X): 156.7 Kelly-Tyson estimation...

In-plane tensile strength (Y): 59

Transverse shear strength (S): 31.8

Dependent parameters

Use strain rate dependent parameters

Help Create

- LS-DYNA implicit & explicit
- Failure indicators:
 - Tsai-Hill 2D & 3D
 - Hashin 2D & 3D
 - Tsai-Wu 2D & 3D
 - Stress based failure
 - Strain based failure
 - ...
- Micro-coupling
- Hybrid-coupling



Linking DIGIMAT to LS-DYNA – DIGIMAT output files

✓ DIGIMAT-output:

- *.log – File

Process documentation

(material data, micro-/hybrid approach, failure information...)

- *.dyn – File

LS-DYNA User material

*MAT_USER_DEFINED_MATERIAL_MODELS

\$	MID	RO	MT	LMC	NHV	IORTHO	IBULK	IG
	1	1.67E-009	41	2	77	0	1	2

\$	IVECT	IFAIL
	1	1

\$	P1 (K)	P2 (G)
	4.46E+004	3.07E+004

- *.mat – File

Material information for calculation

```

ANALYSIS
name = DIGIMATinfo
type = mechanical
loading_name = Mechanical
finite_strain = off
finite_rotation = offload = LS-DYNA/Explicithomogenization_model = Mori_Tanaka
hybrid_methodology = on
hybrid_quasistatic_strain_rate = 1.0000000000000000e-006
hybrid_dynamic_strain_rate = 1.0000000000000000e+002
hybrid_strain_range = 1.5000000000000000e-001
hybrid_failure_strain_rate = 1.0000000000000000e-006
FPGF_failure_indicator = FailureIndicator1
FPGF_failure_weight = 1.0000000000000000e+000
FPGF_critical_fraction = 8.0000000000000000e-001
FPGF_refinement = on
    
```



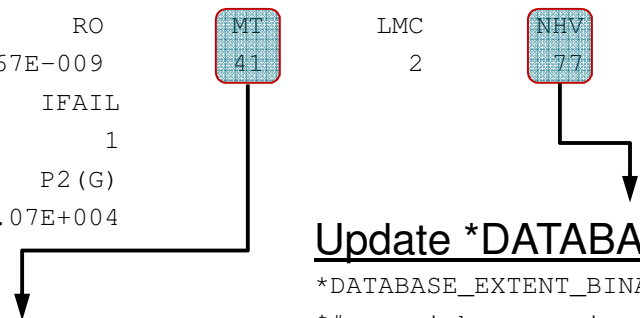
Linking DIGIMAT to LS-DYNA – update LS-DYNA model

Copy *.dyn material card into your input deck

*MAT_USER_DEFINED_MATERIAL_MODELS

```

$      MID      RO      MT      LMC      NHV      IORTHO      IBULK      IG
      1 1.67E-009      41      2      77      0      1      2
$      IVECT      IFAIL
      1      1
$      P1(K)      P2(G)
      4.46E+004 3.07E+004
    
```



Update *DATABASE EXTENT BINARY

*DATABASE_EXTENT_BINARY

```

$#      neiph      neips      maxint      strflg      sigflg      epsflg      rltflg      engflg
      0      77      12      1      1      1      1      1
$#      cmpflg      ieverp      beamip      dcomp      shge      stssz      n3thdt      ialemat
      0      0      0      1      1      1      2      0
    
```

Use a *KEYWORD ID

Rename *.mat File into ***41.mat** – File

Define the shell section by computing the stiffness of every layer as function of the position of the layers in Moldflow:

*PART_COMPOSITE

\$# title

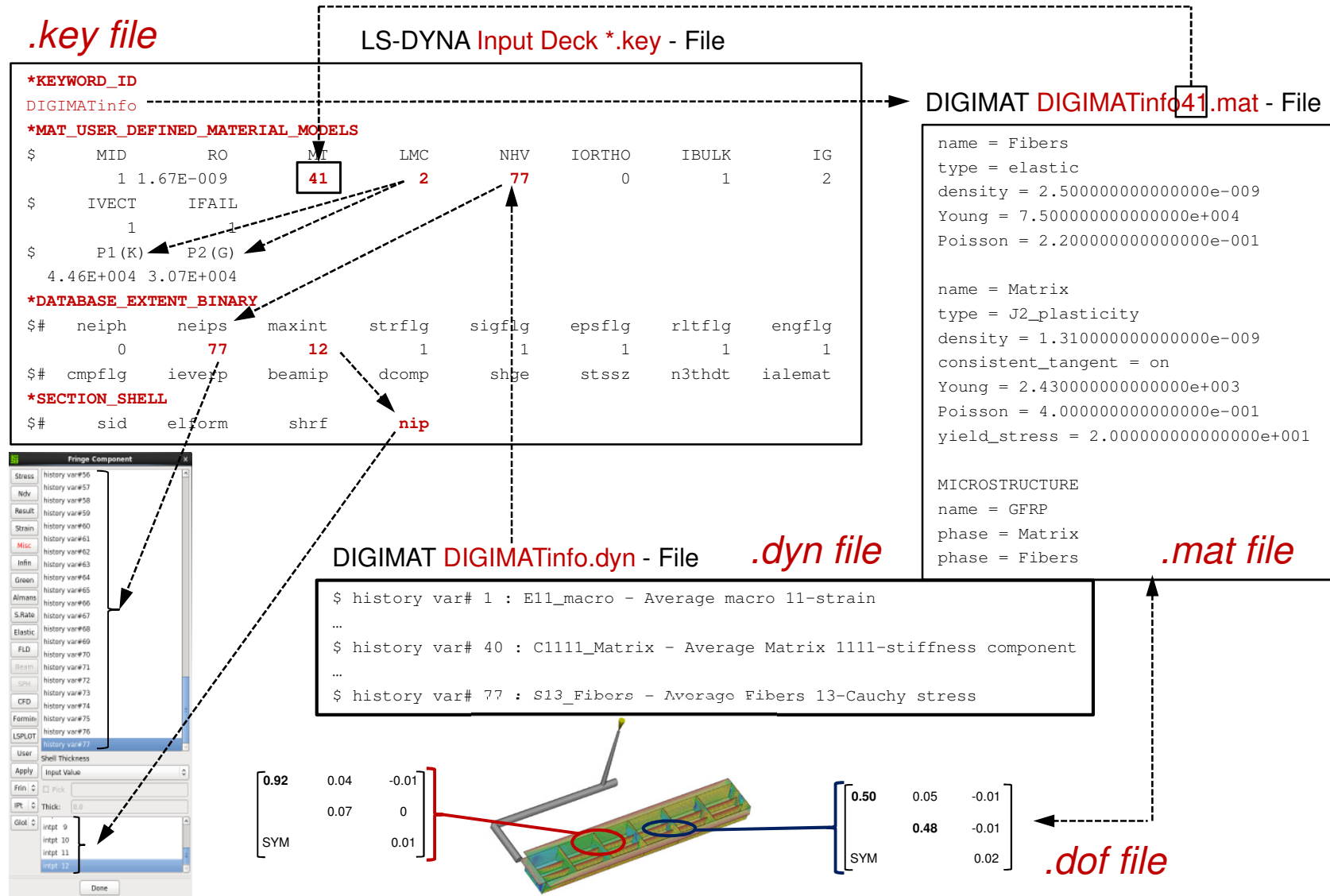
Example

```

$#      pid      elform      shrf      nloc      marea      hgid      adpopt      ithelfrm
      2      2      0.833330      0.000      0.000      1      0      0
$#      mid1      thick1      b1      ithid1      mid2      thick2      b2      ithid2
      1 0.180000      0.000      0      1 0.213000      0.000      0
      1 0.241500      0.000      0      1 0.267000      0.000      0
      1 0.289500      0.000      0      1 0.309000      0.000      0
      1 0.309000      0.000      0      1 0.289500      0.000      0
      1 0.267000      0.000      0      1 0.241500      0.000      0
      1 0.213000      0.000      0      1 0.180000      0.000      0
    
```



Linking DIGIMAT to LS-DYNA – update LS-DYNA model

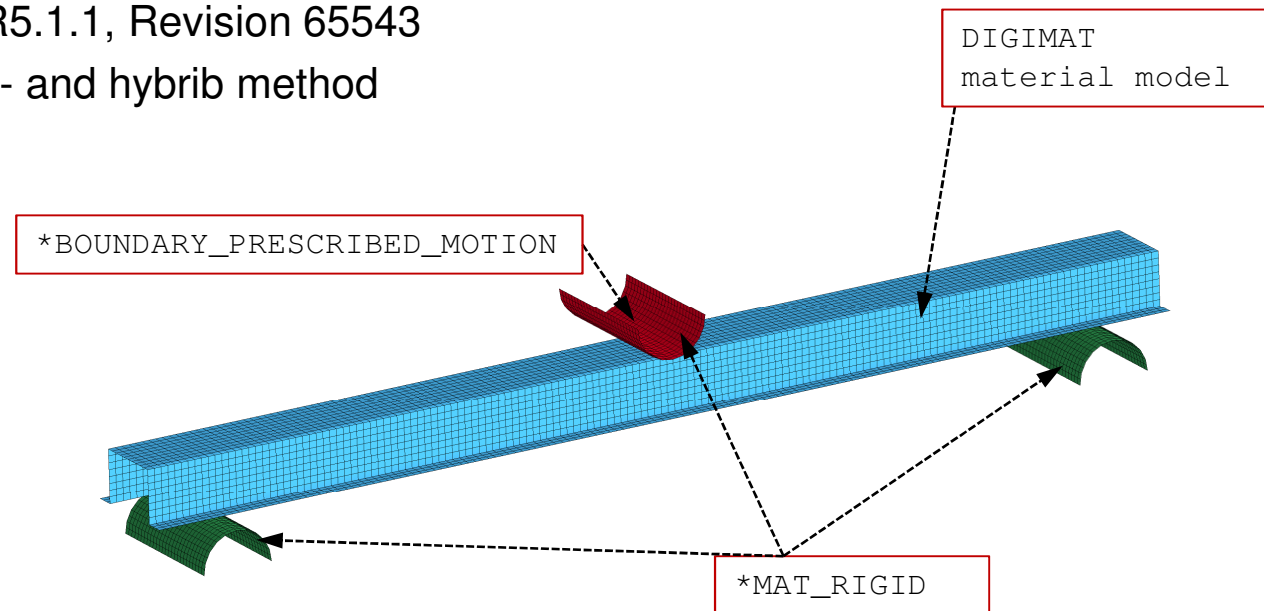




Linking DIGIMAT to LS-DYNA – Test example

Test example

- Classical three point bending test
- Results: nodal displacement at impactor, contact force at supporters
- Shell elements ETYP = 2, 4800 elements using DIGIMAT-material, 12 IP over the thickness (*PART_COMPOSITE)
- Calculation parameter: 0.2 sec., dt2ms: 4.5E-07
- LS-DYNA mpp971s, R5.1.1, Revision 65543
- Calculation with micro- and hybrid method





Linking DIGIMAT to LS-DYNA – Test example

- Four cores used
- LS-DYNA mpp971s, R5.1.1, Revision 65543
- Calculation parameter: 0.2 sec., dt2ms: 4.5E-07

Standard LS-DYNA Material

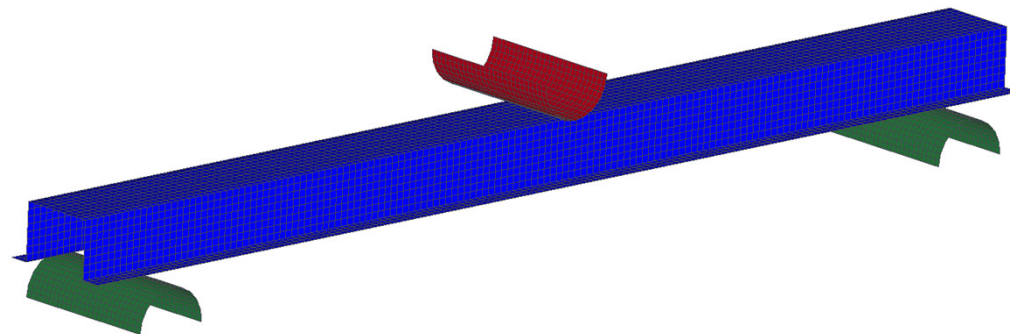
- Calculation time: 5h 15min

HYBRID – results:

- Calculation time: 5h 15min

MICRO – results:

- Calculation time: ~52h 40min



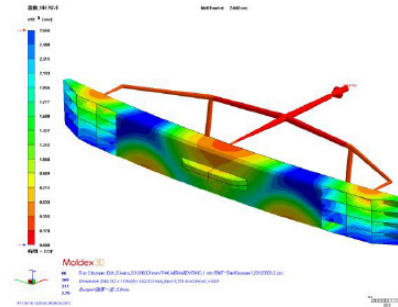


Linking DIGIMAT to LS-DYNA – full vehicle testing

Full vehicle **System Level**

✓ Pedestrian safety

- Bumper beam

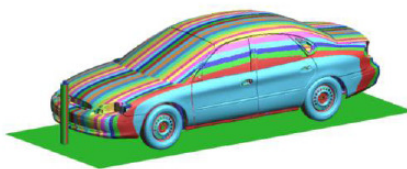


JSOL CORPORATION

NTT DATA Global IT innovator



Elements	3.1 Mio
Ave. elem size	5.0 [mm]
Min. time step	0.25 [µsec]
DIGIMAT	0.84% (26.000)



10 domains have no DIGIMAT elements

DIGIMAT elements in 22 domains



Linking DIGIMAT to LS-DYNA – full vehicle testing

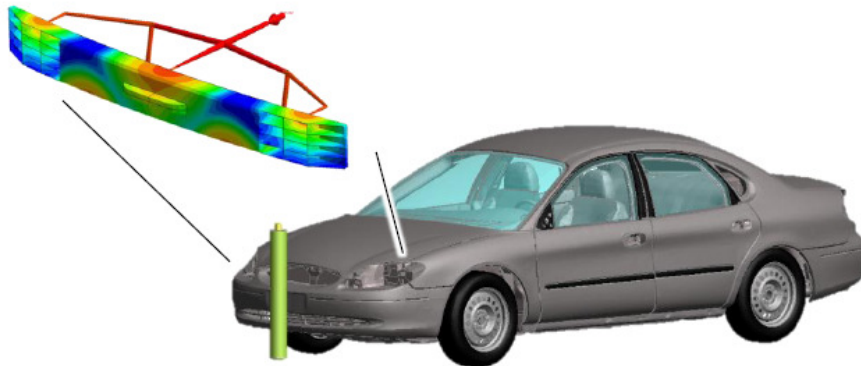
Full vehicle System Level

✓ **Acceptable increase of calculation time**

- 9 → 14 hours on 32 cores
- **Only 8 hours on 64 cores**

✓ **Loss in efficiency for ISOTROPIC**

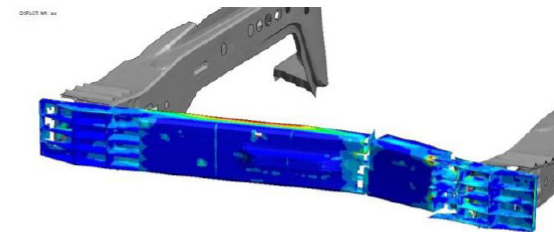
- On 64 cores
- Overhead of communication



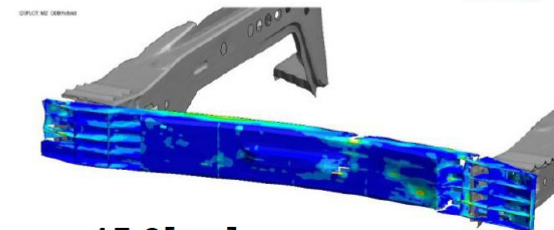
JSOL CORPORATION

NTT DATA Global IT Incubator
NTT DATA Group

ISO



ANISO



15.0 [ms]

	16 cores	32 cores	64 cores
ISOTROPIC (improved)	17h 59min	9h 17min	10h 00min
HYBRID (default)		42h 31min	
HYBRID (improved)		14h 16min	
HYBRID (optimized)	26h 37min	12h 05min	8h 15min
Micro (improved)		152h 51min	



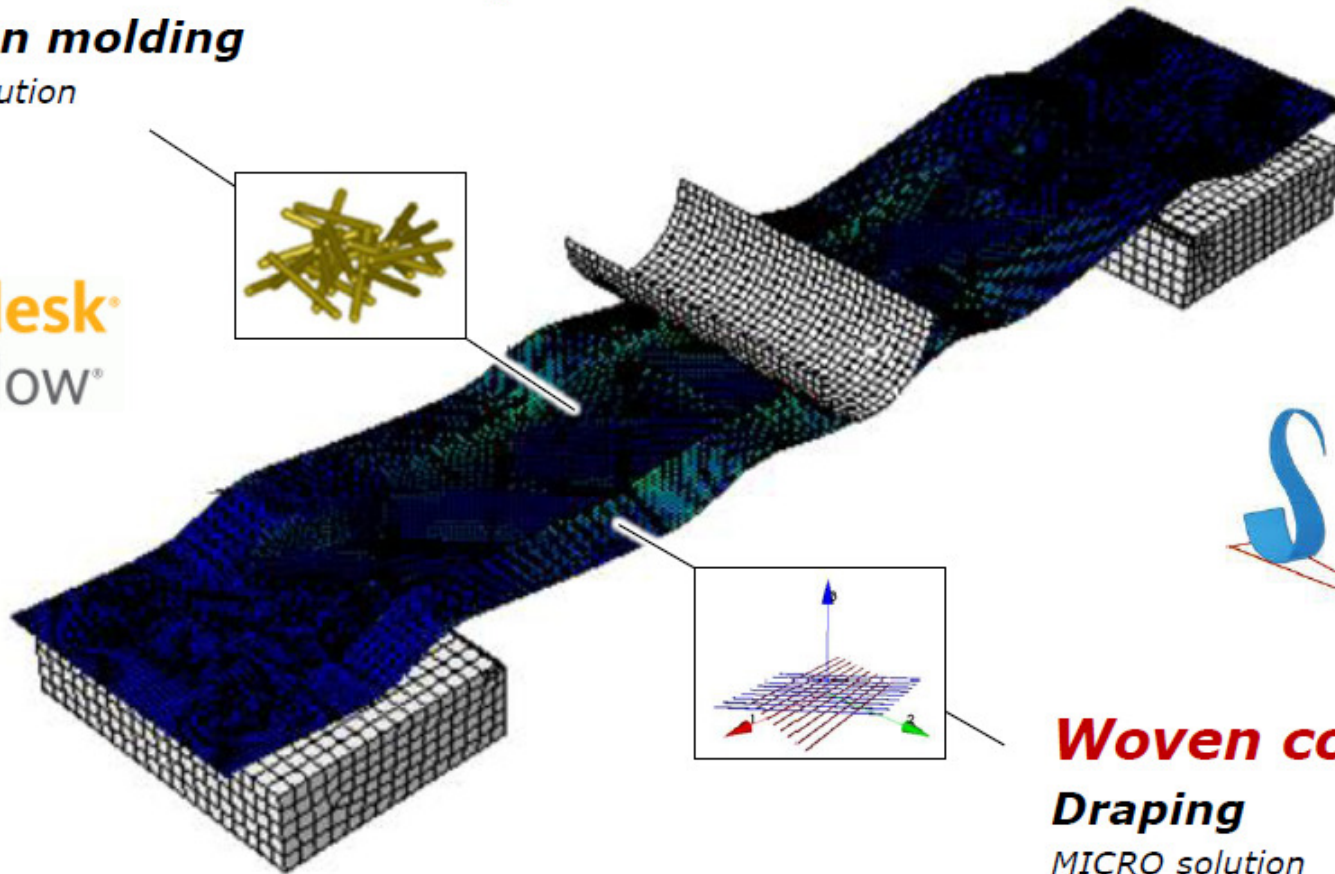
Linking DIGIMAT to LS-DYNA – woven composites

Short fiber reinforced plastics

Injection molding

HYBRID solution

Autodesk
Moldflow®



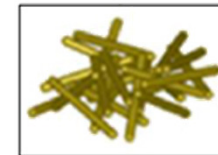
Woven composite

Draping

MICRO solution

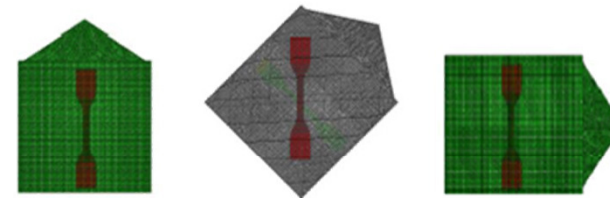


Linking DIGIMAT to LS-DYNA – woven composites



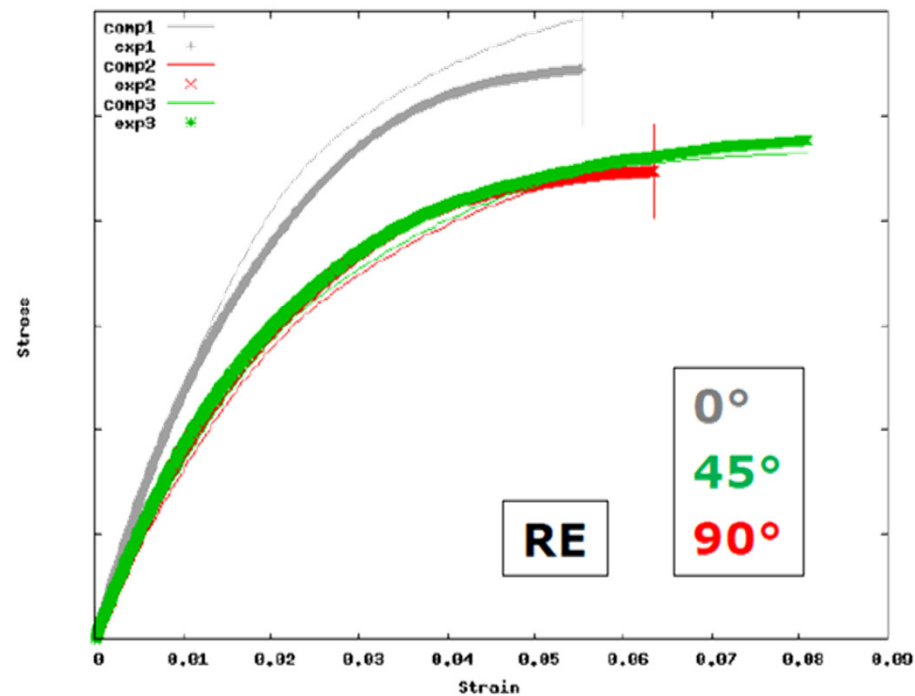
∞ Overmolded Beam

✓ Short fiber reinforced plastics



- Reverse engineering

- Anisotropic
 - » From plate
- Elastoplastic
- Global fit
 - » 0°
 - » 45°
 - » 90°

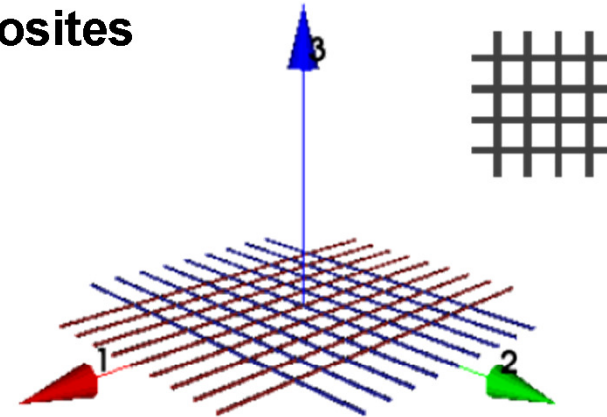




Linking DIGIMAT to LS-DYNA – woven composites

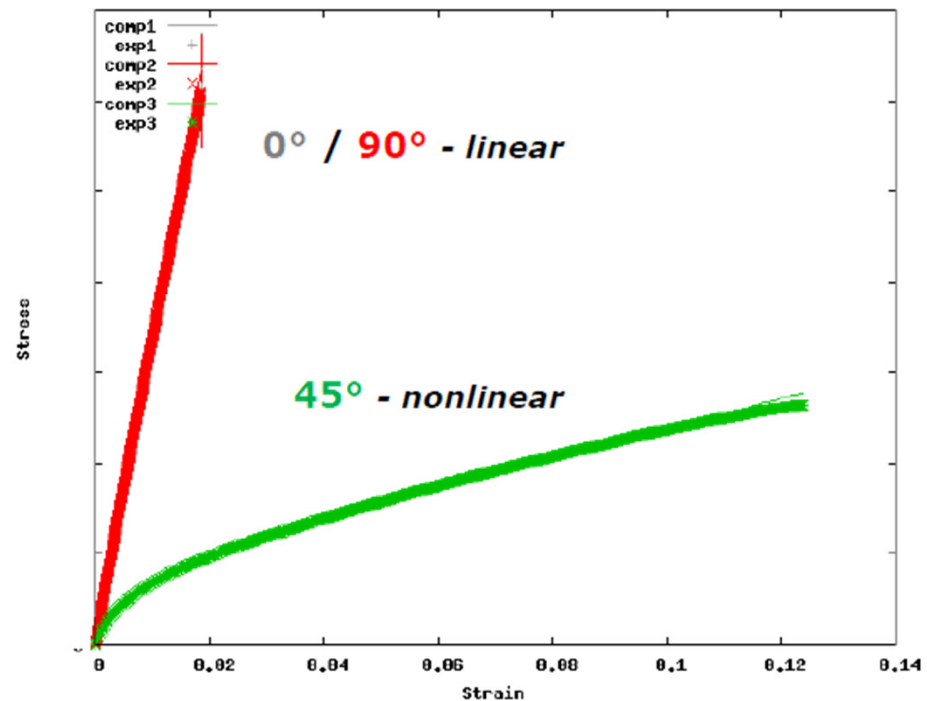
∞ Overmolded Beam

✓ Woven composite



- Measurements

- Anisotropic
 - » From specimen
- Elastoplastic
- Global fit
 - » 0°
 - » 45°
 - » 90°



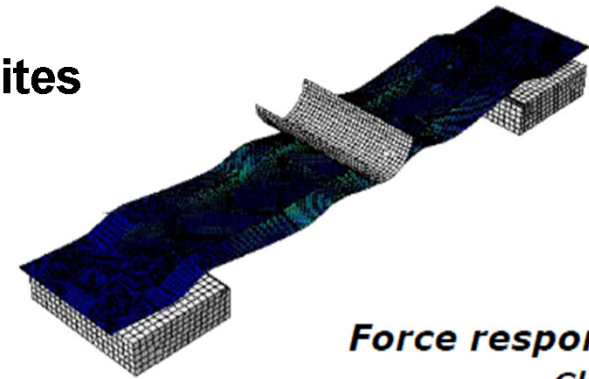


Linking DIGIMAT to LS-DYNA – woven composites

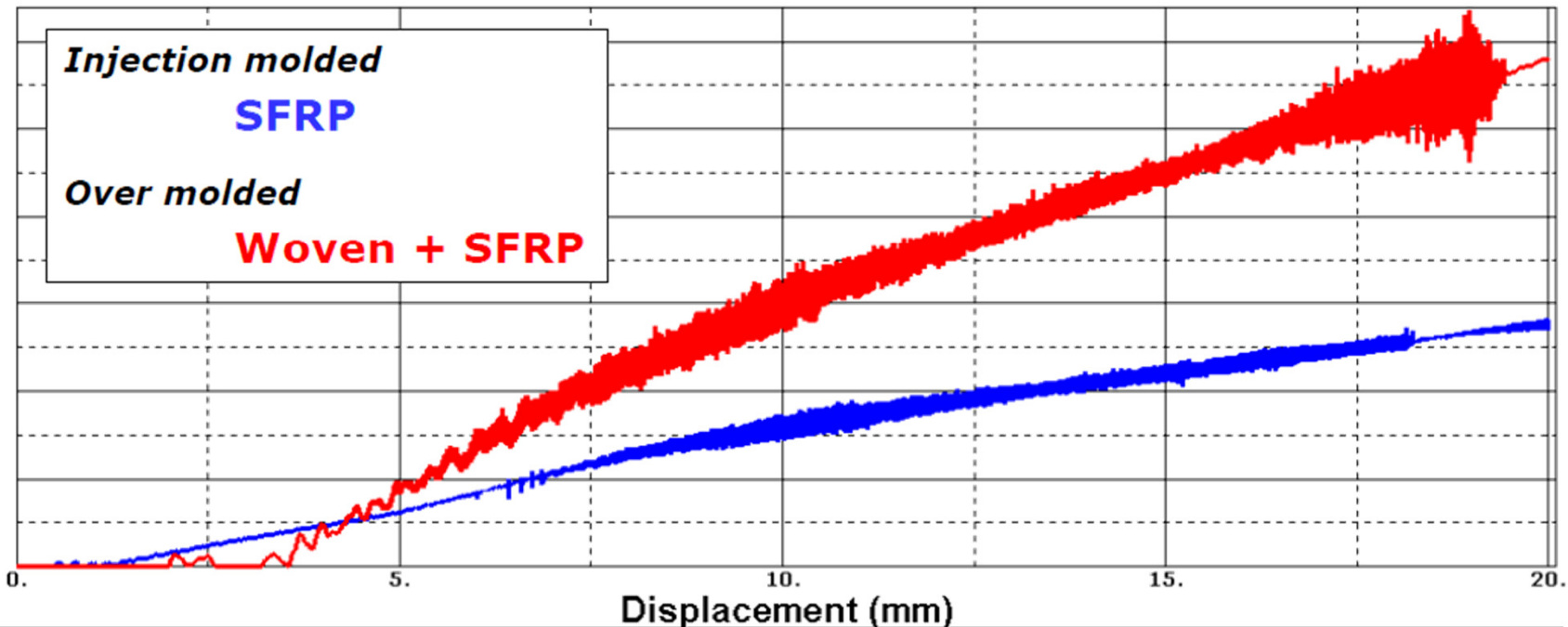
∞ Overmolded Beam

✓ Coupled analysis

- Injection molded vs. Over molded beam

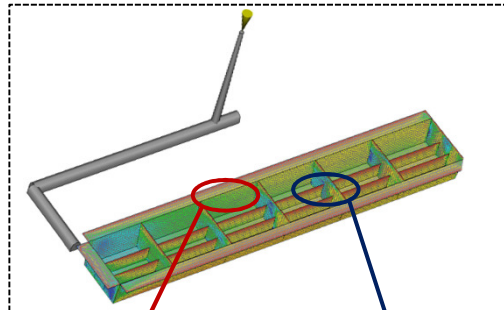


Force response
Global



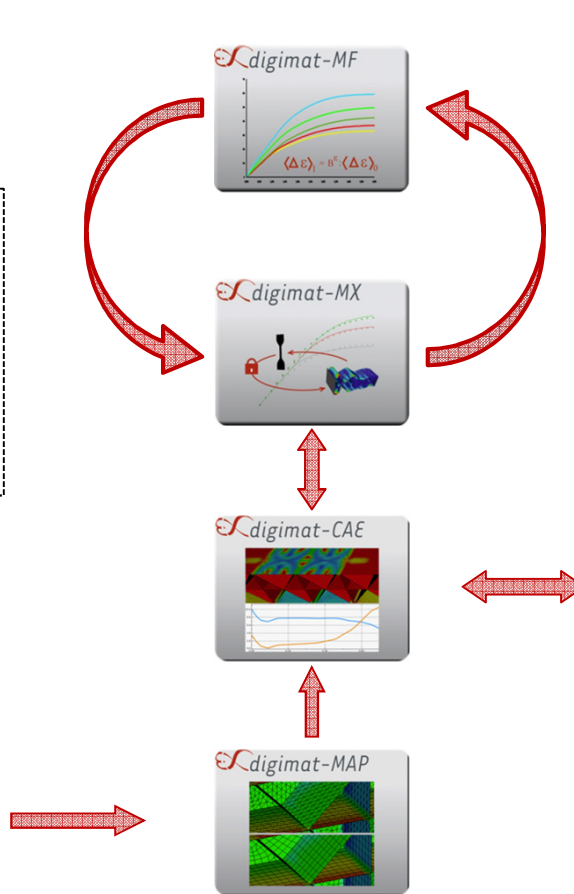
Micro – Macro Modeling: Linking DIGIMAT with LS-DYNA

injection molding simulation



0.92	0.04	-0.01	0.50	0.05	-0.01
	0.07	0		0.48	-0.01
SYM		0.01	SYM		0.02

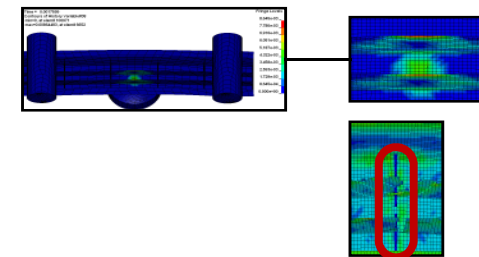
different fiber orientation tensors



	LS-Dyna
Shell	1 (Hughes–Liu), 2 (Belytschko-Tsay), 4 (Triangular Shell), 6 (S/R Hughes–Liu), 16 (Fully integrated) -> Not for triangular elements
Solid	1 (Constant Stress), 2 (S/R Solid), 3 (Quadratic 8 nodes), 4 (S/R Tetrahedron), 10 (1pt Tetrahedron)

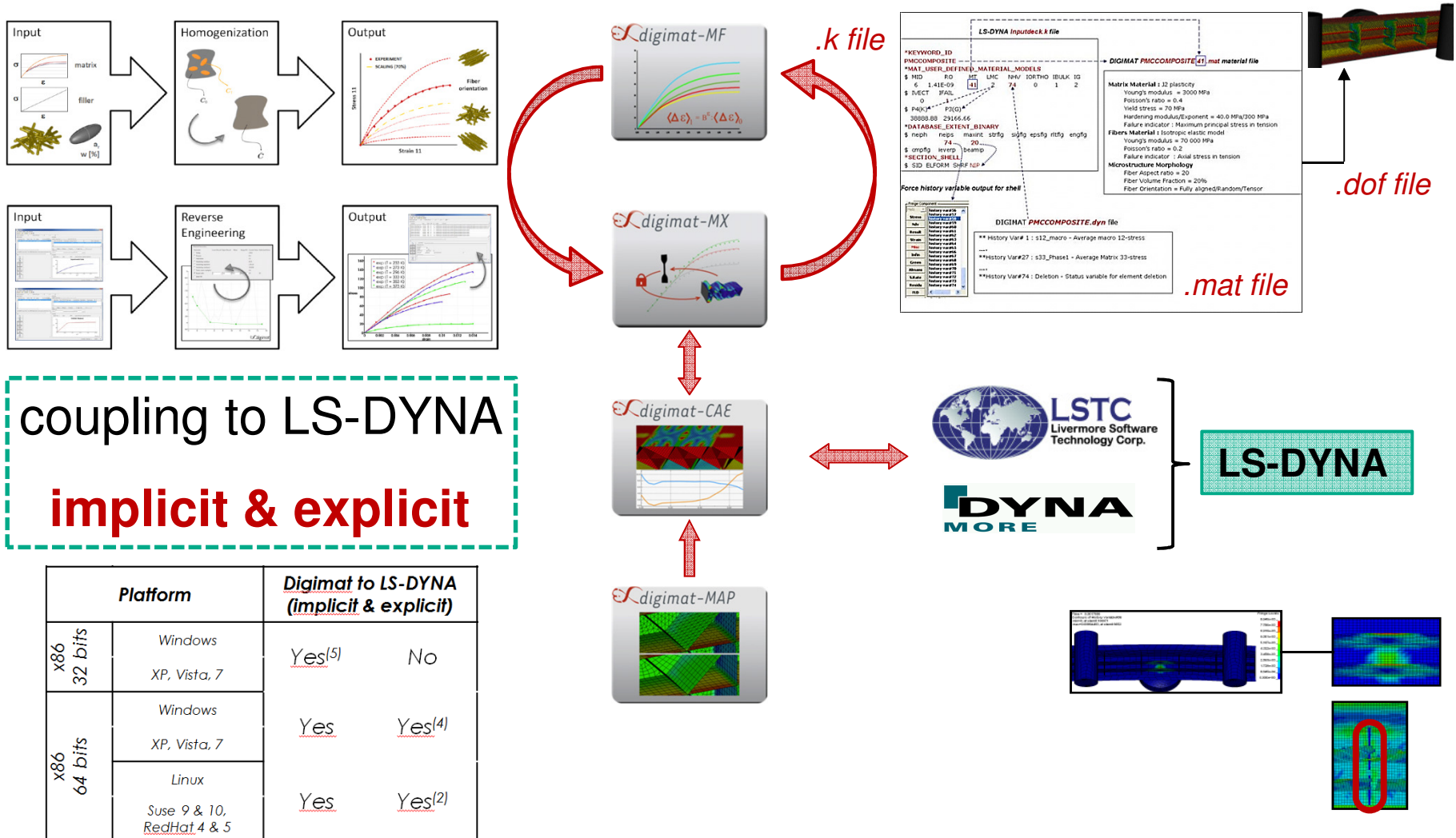


LS-DYNA



[Dr. J. Seyfarth: e-Xstream]

Micro – Macro Modeling: Linking DIGIMAT with LS-DYNA



coupling to LS-DYNA
implicit & explicit

Platform		Digimat to LS-DYNA (implicit & explicit)	
x86 32 bits	Windows XP, Vista, 7	Yes ⁽⁵⁾	No
	Windows XP, Vista, 7	Yes	Yes ⁽⁴⁾
x86 64 bits	Linux Suse 9 & 10, RedHat 4 & 5	Yes	Yes ⁽²⁾

[Dr. J. Seyfarth: e-Xstream]



FIN